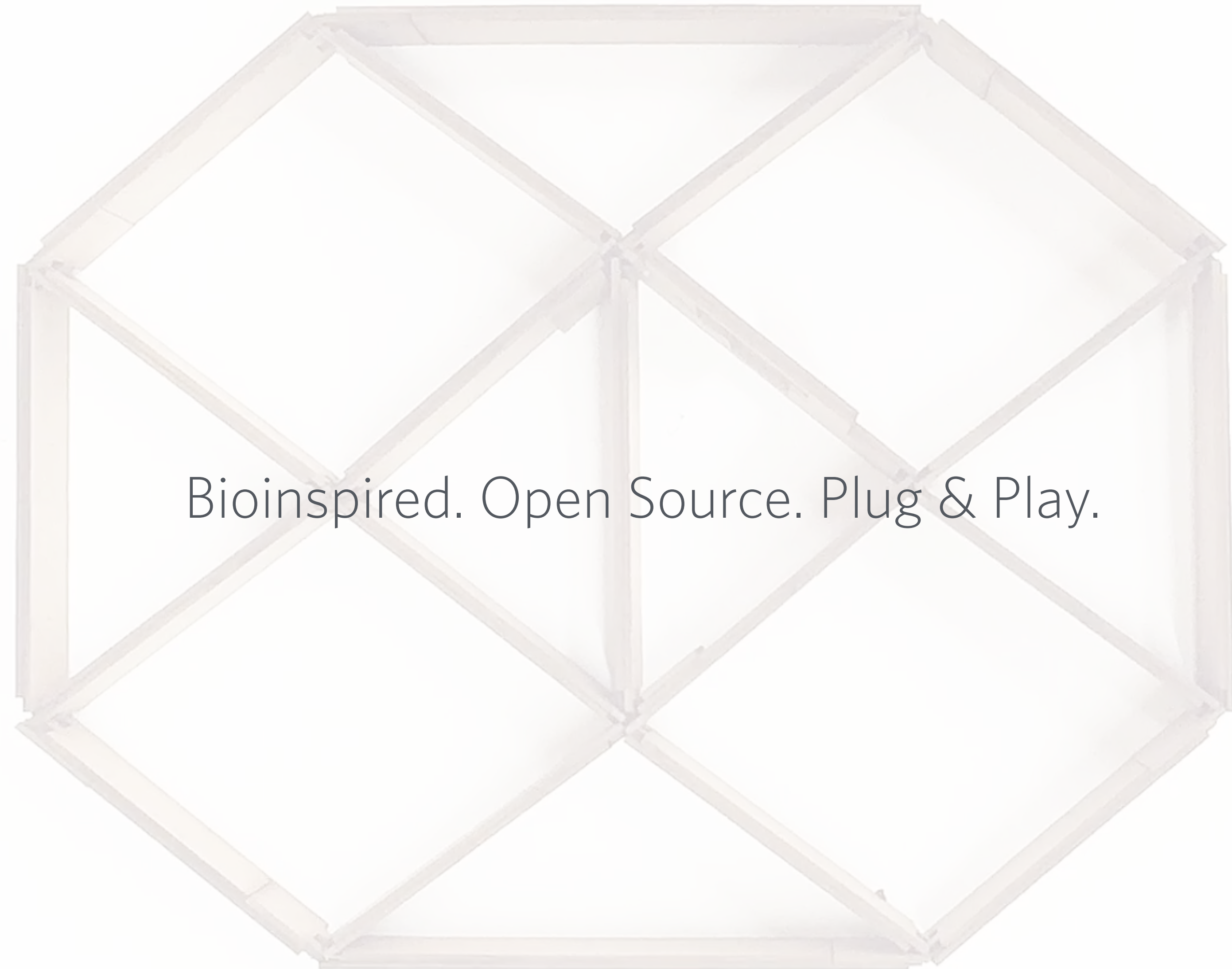


OpenWalk

6378, Informal Robotics, Fall 2015.

Nono Martínez Alonso
Jose Guillermo Saavedra Roman
Enol Vallina Fernandez

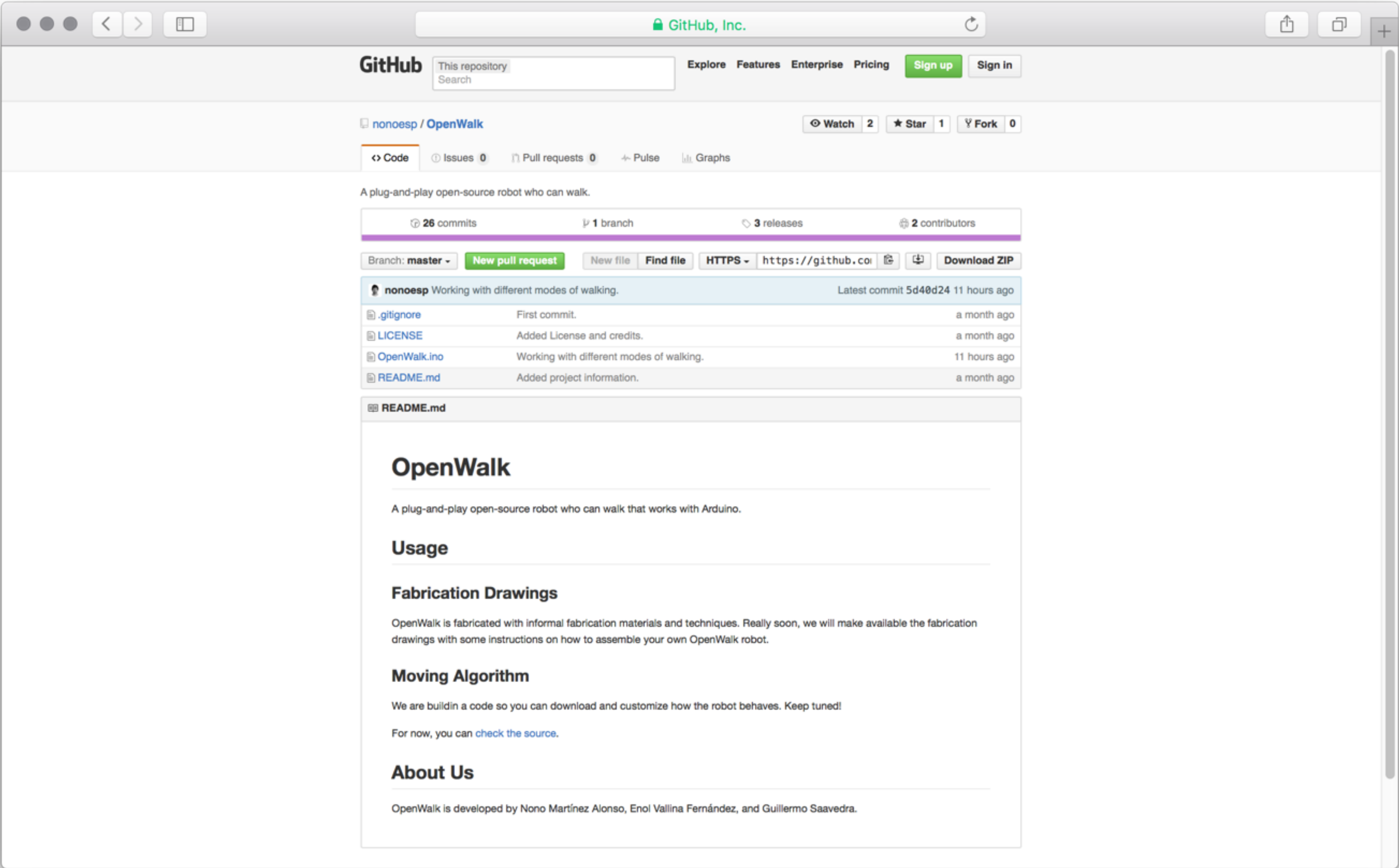


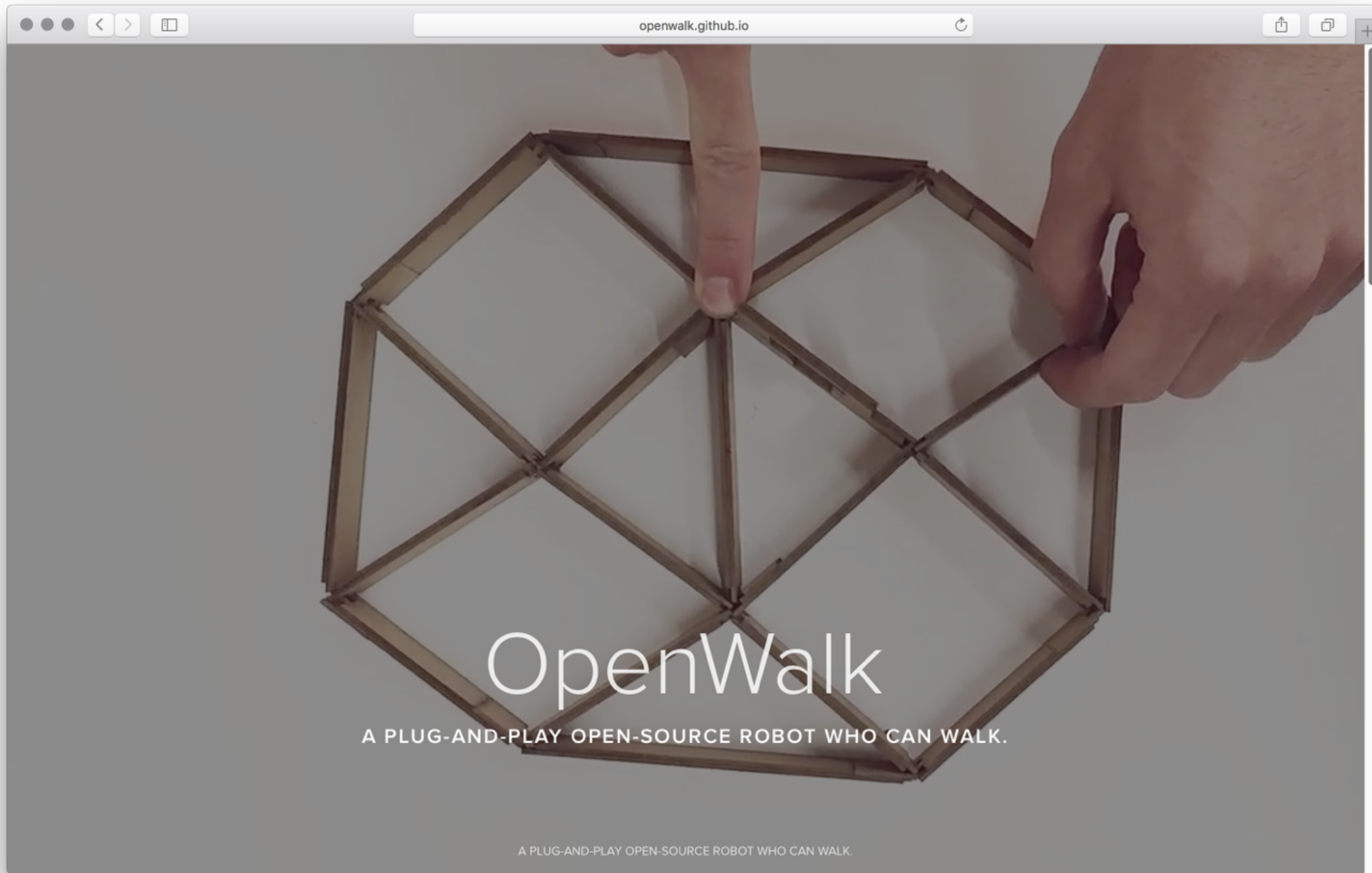




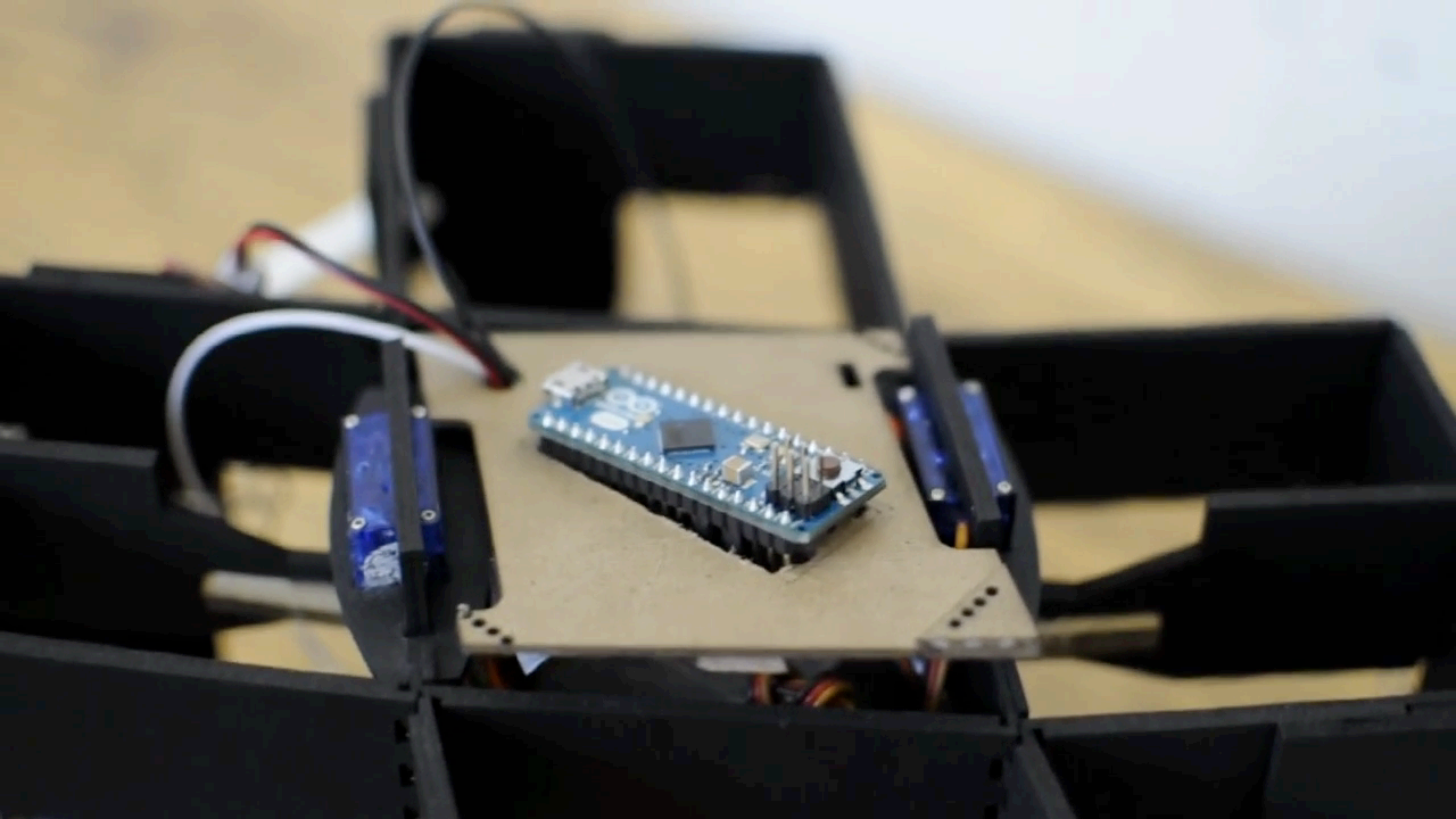


Project Ara. Google



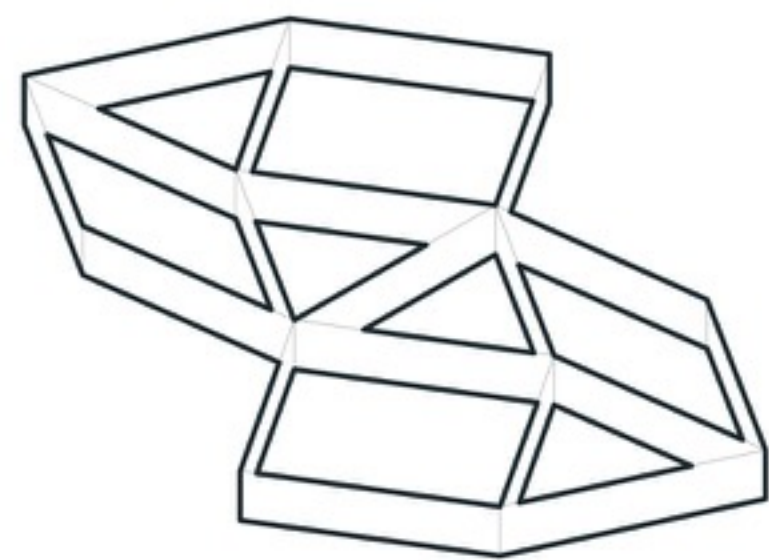


Device.

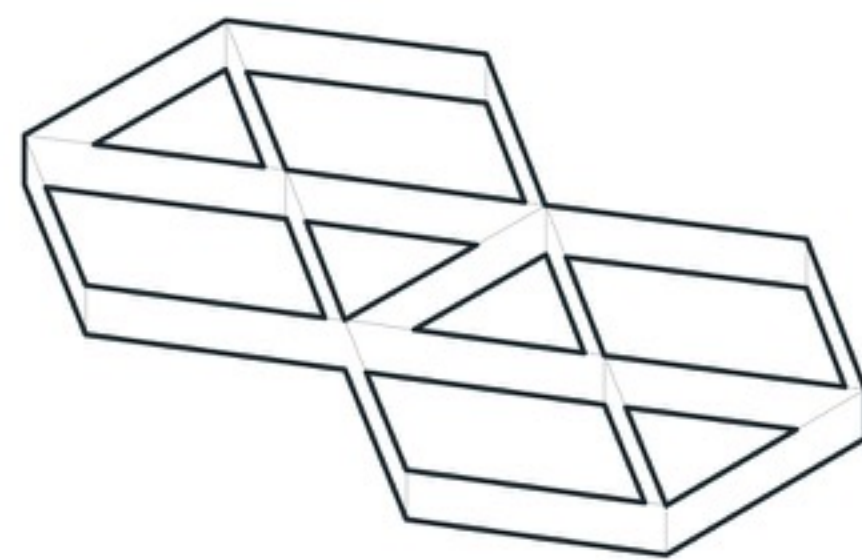


Kinematics.

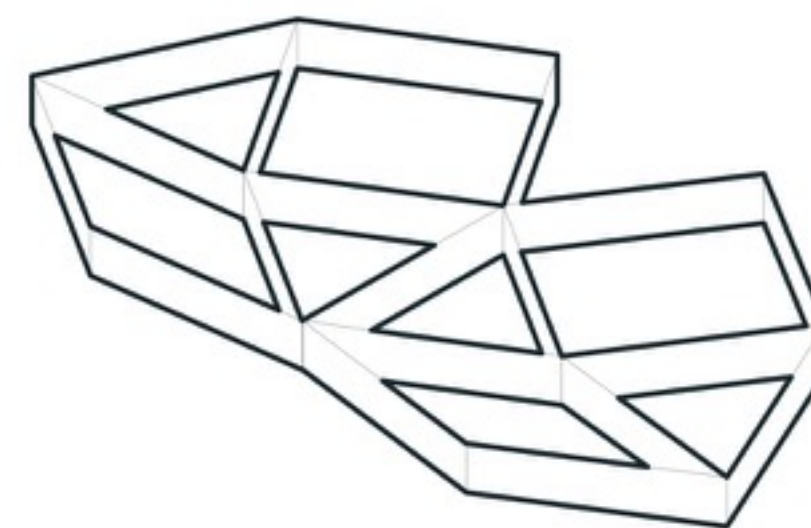
Body.



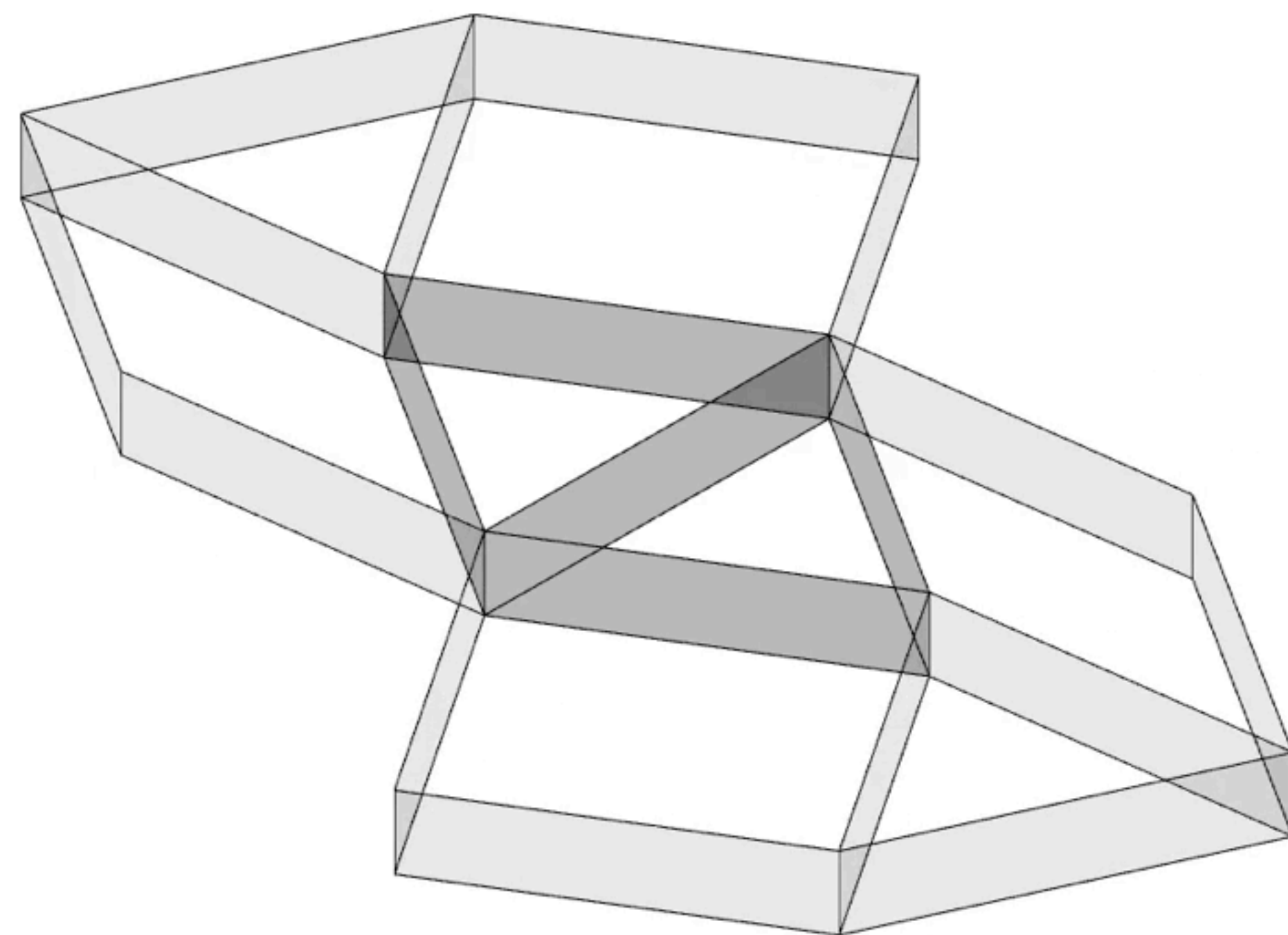
Asymmetric

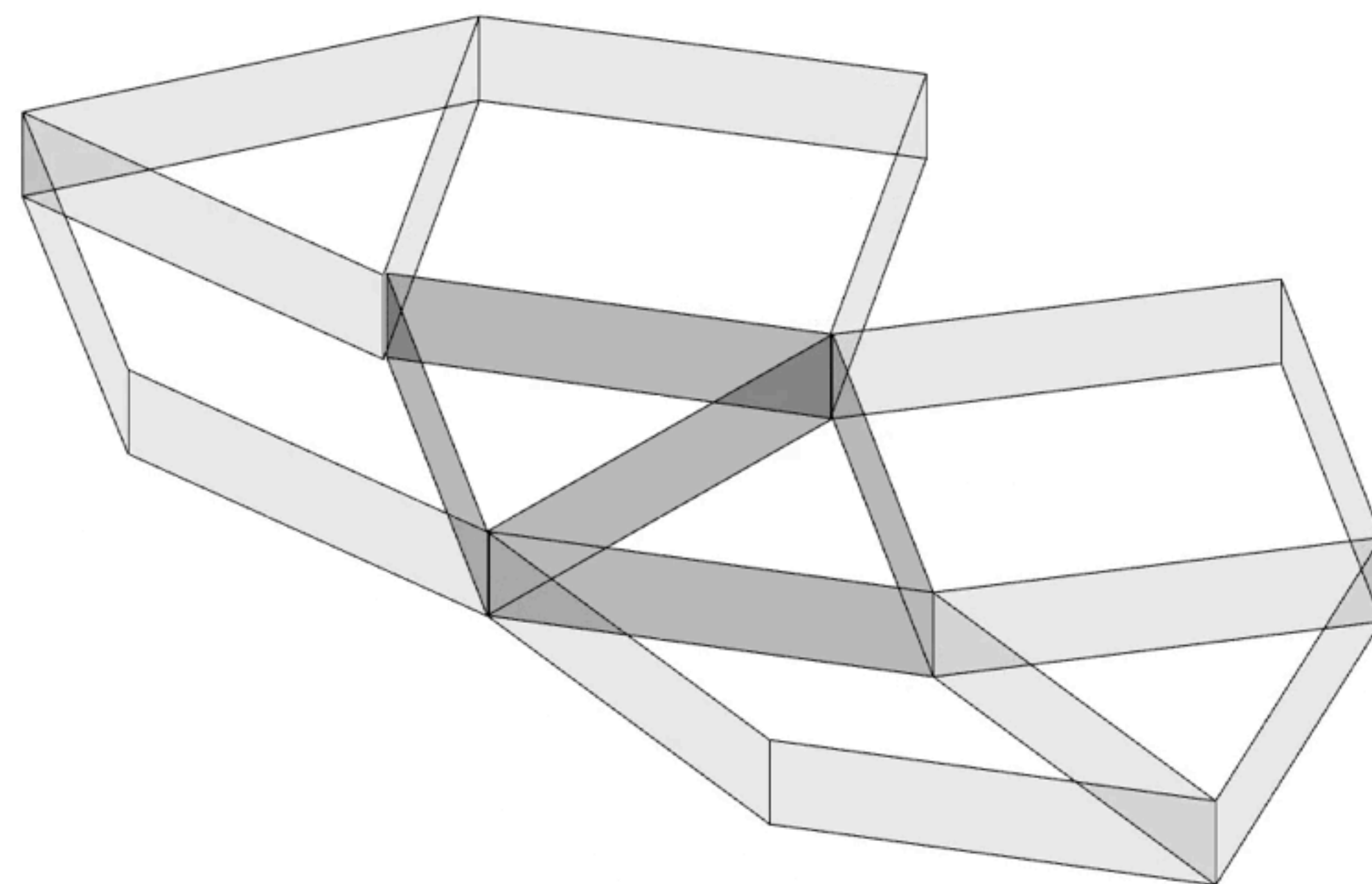


Rest

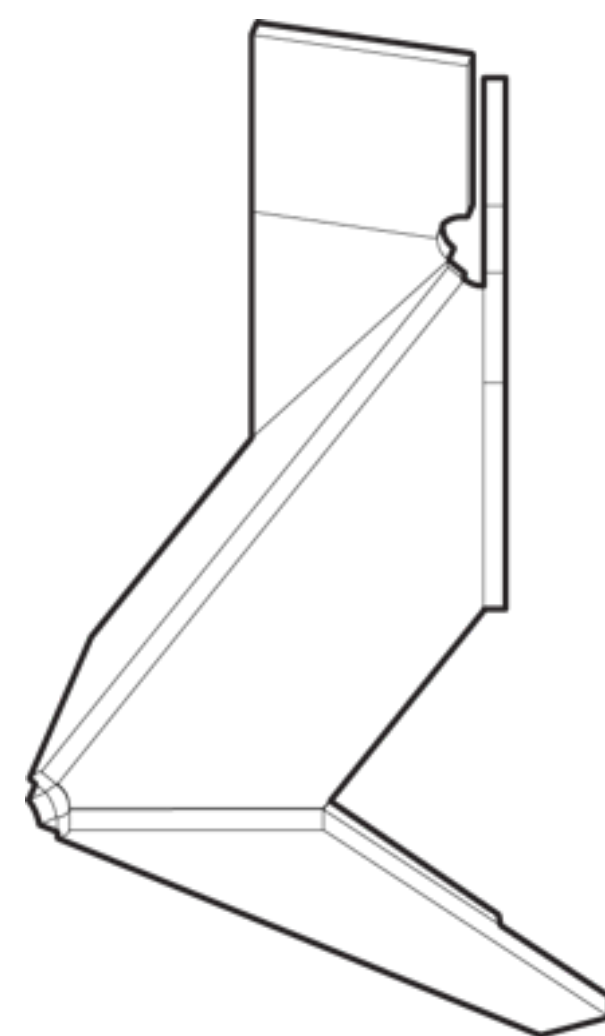


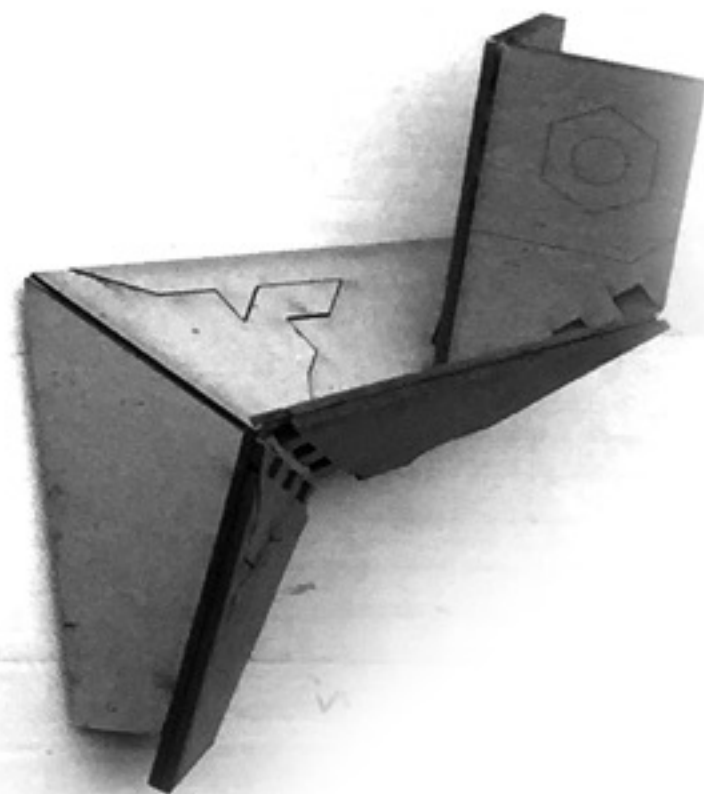
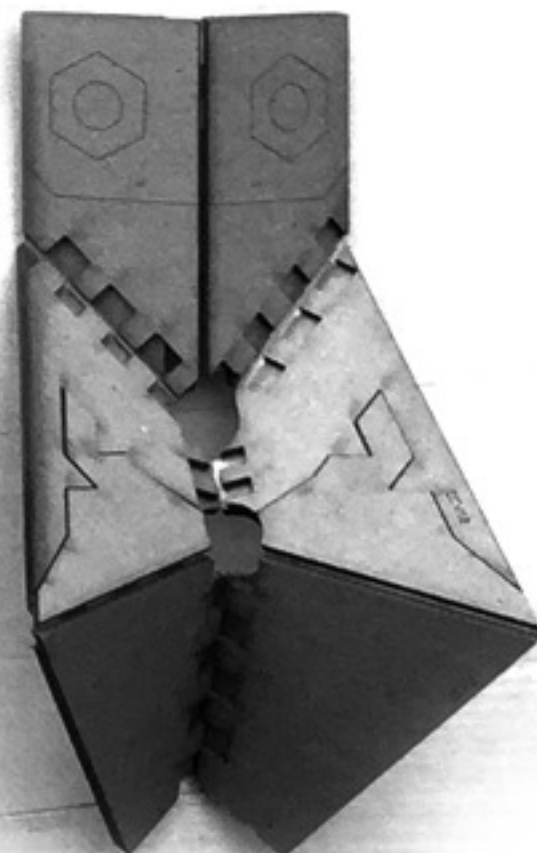
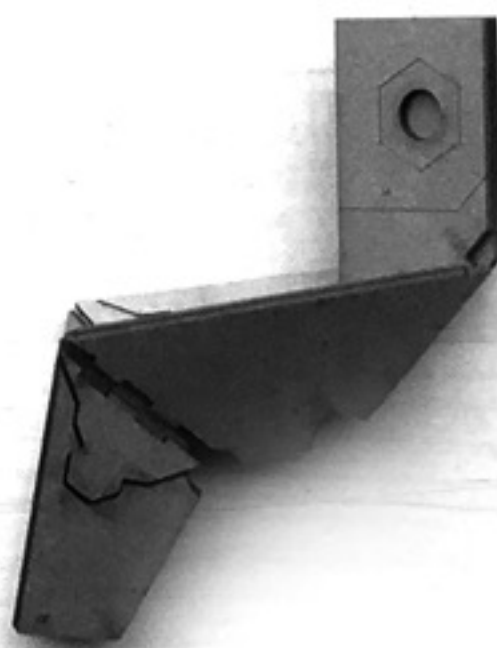
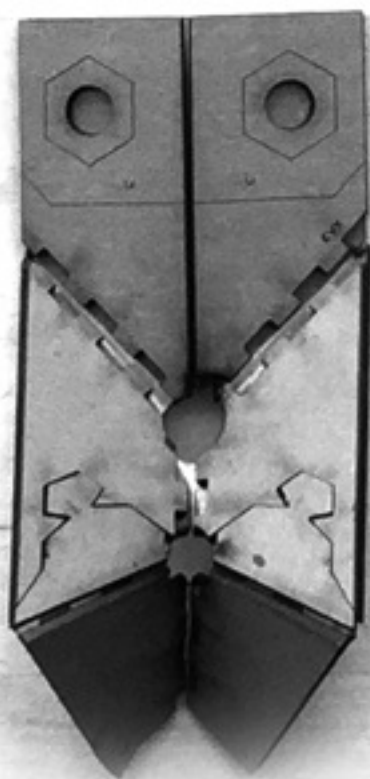
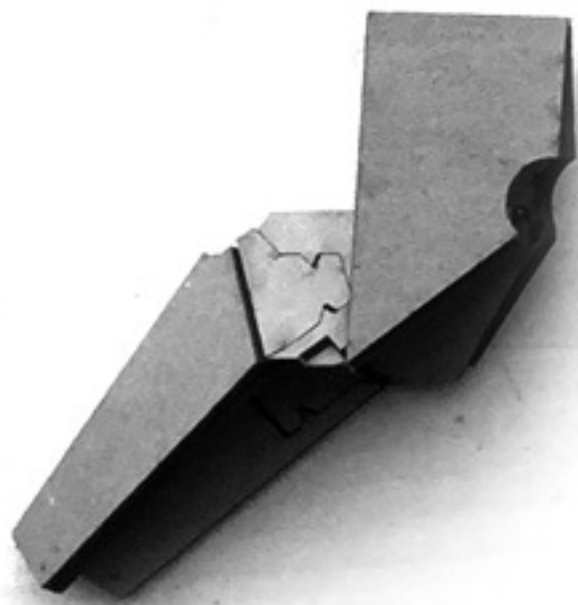
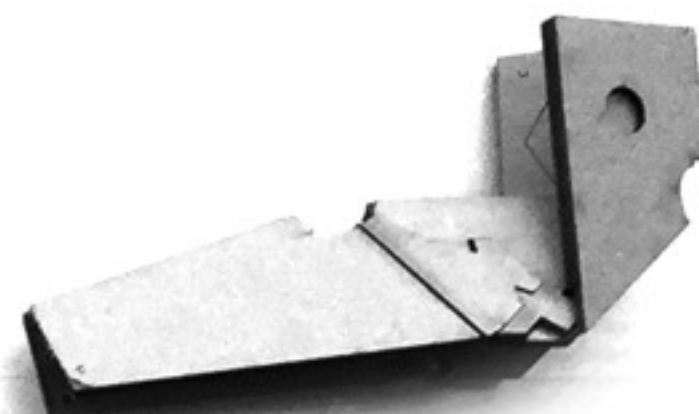
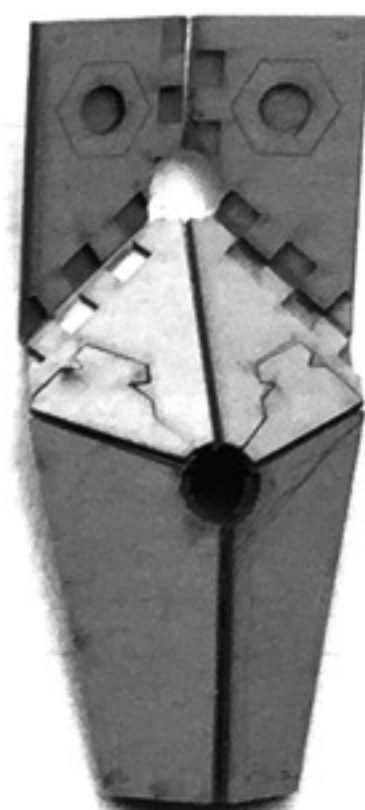
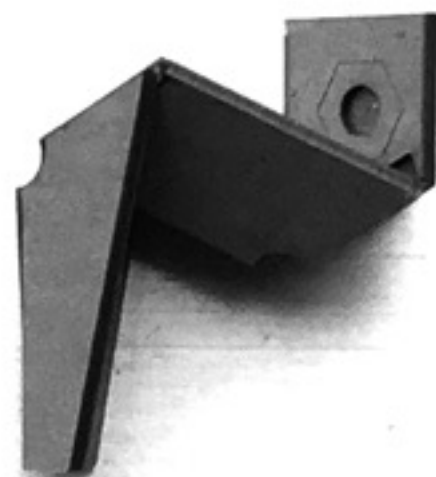
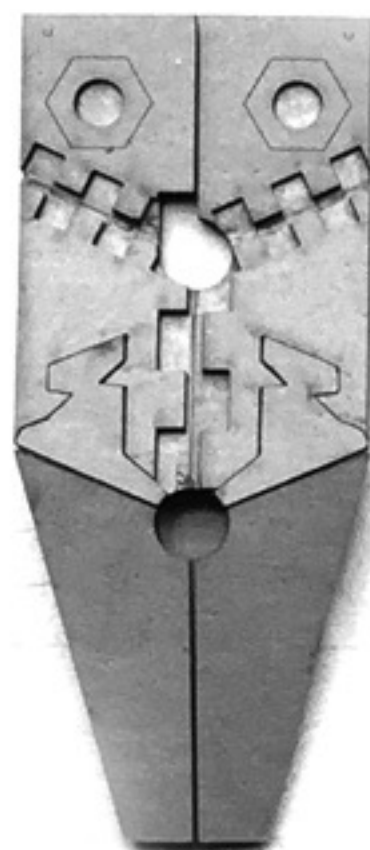
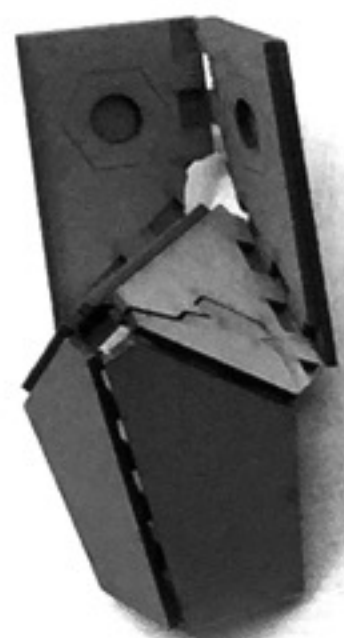
Symmetric

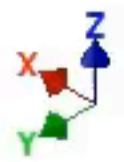
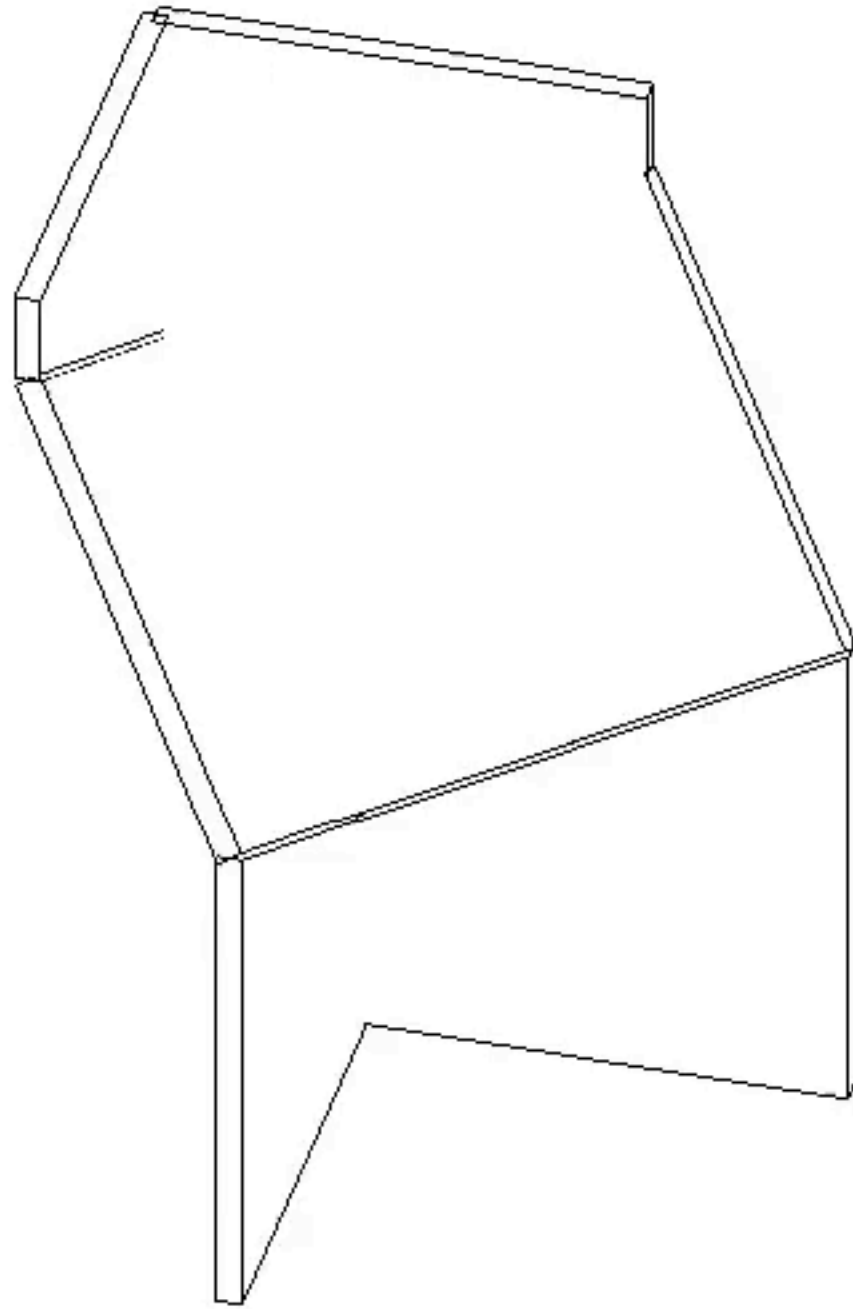


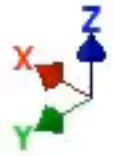
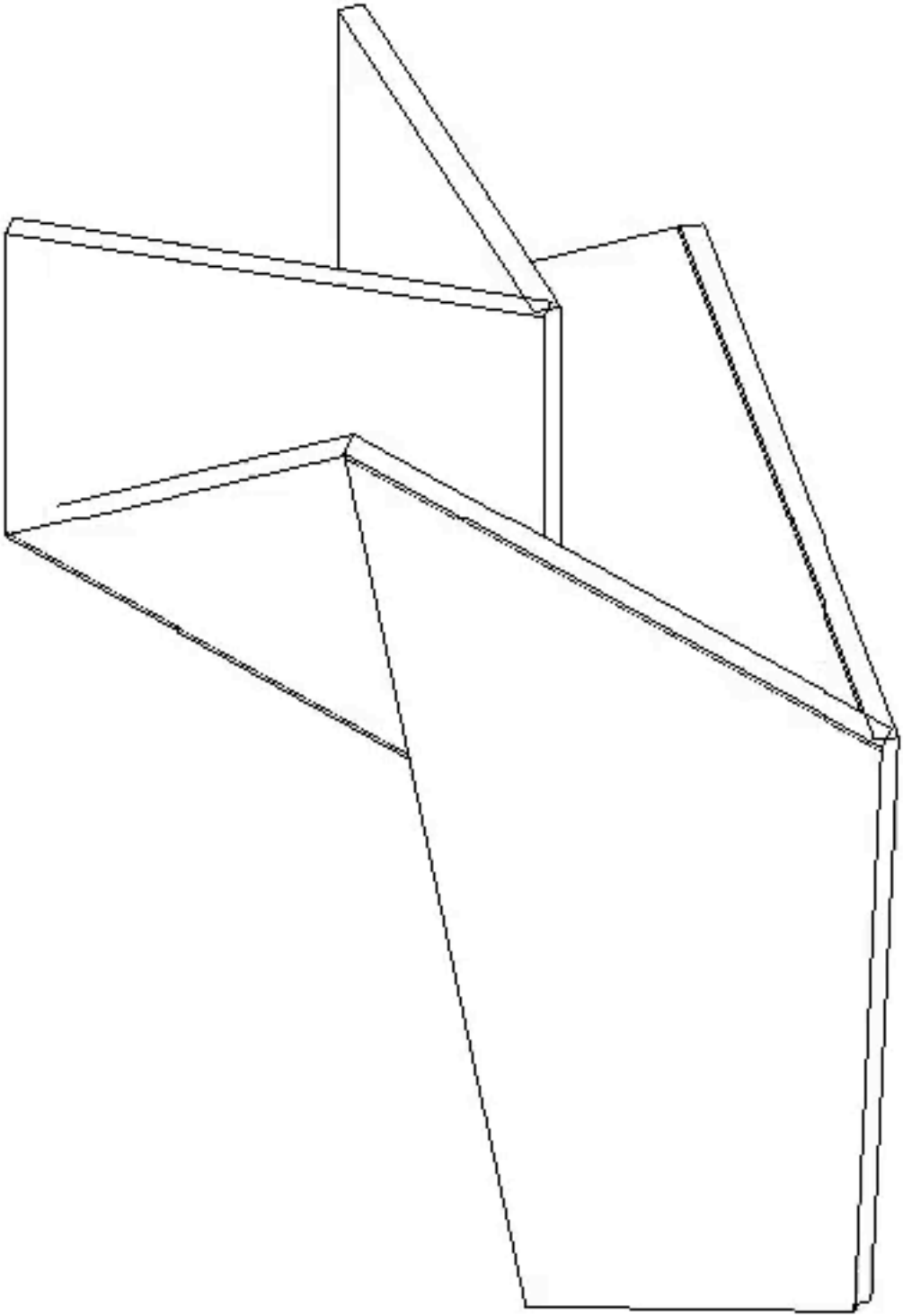


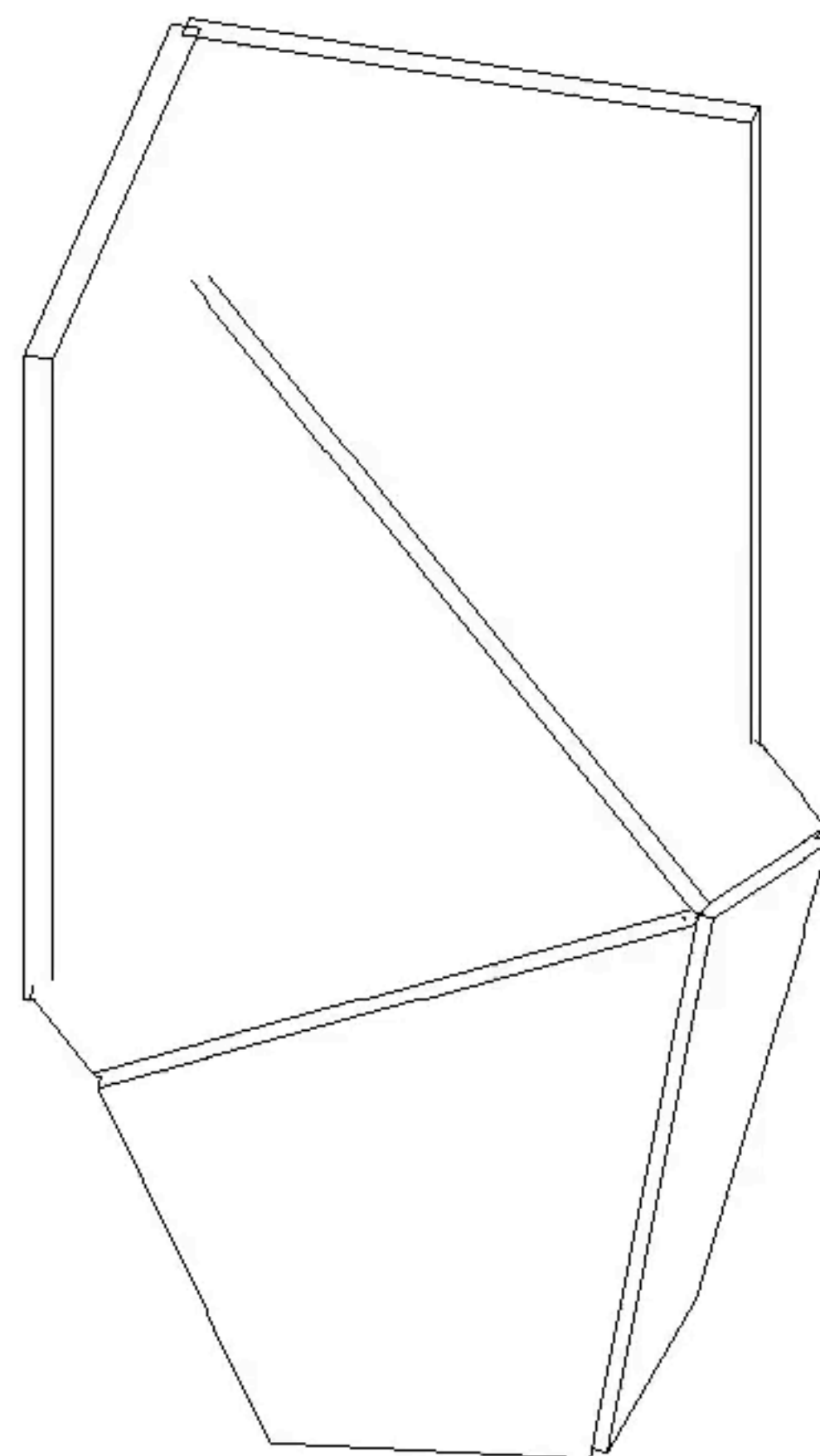
Legs.



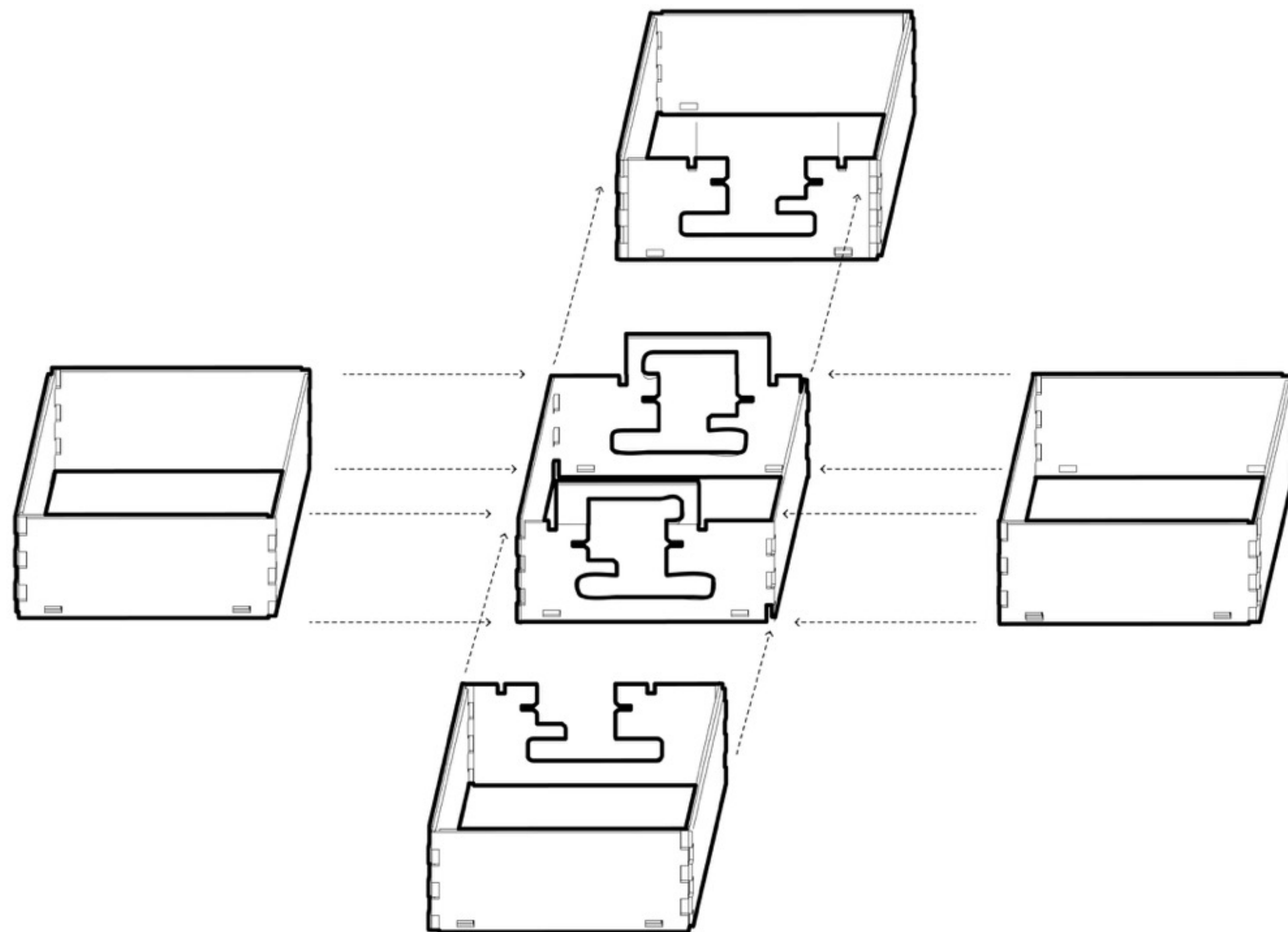


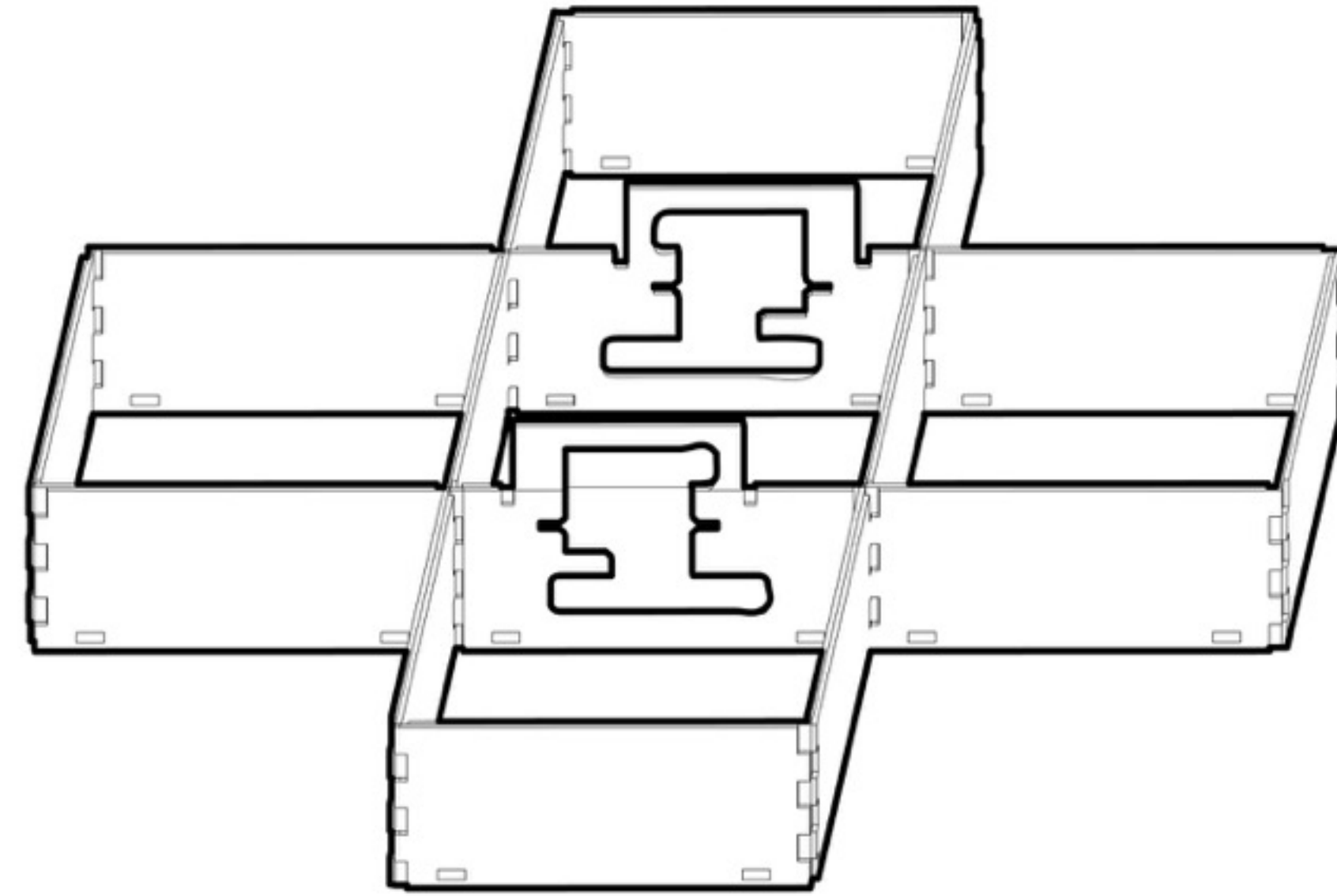


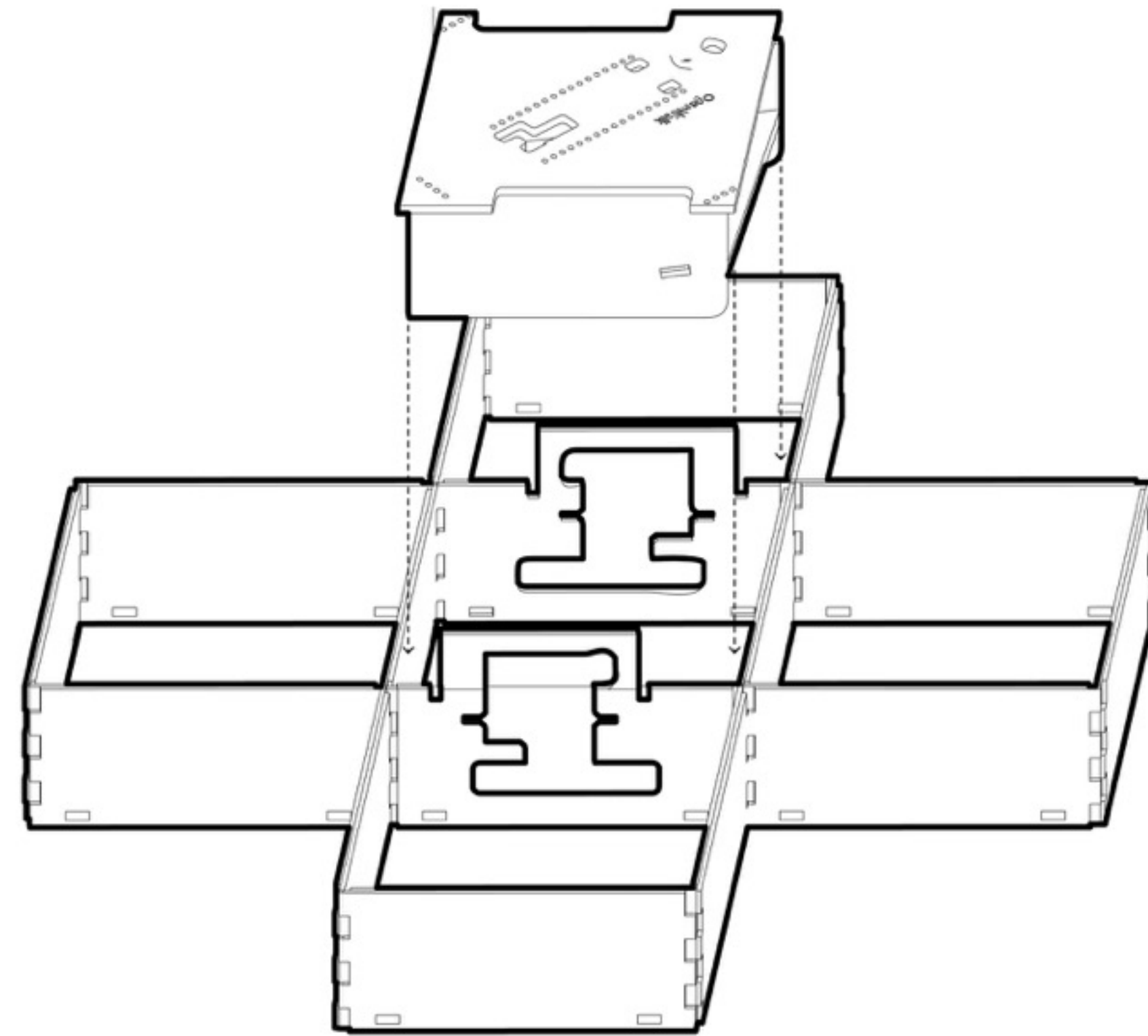


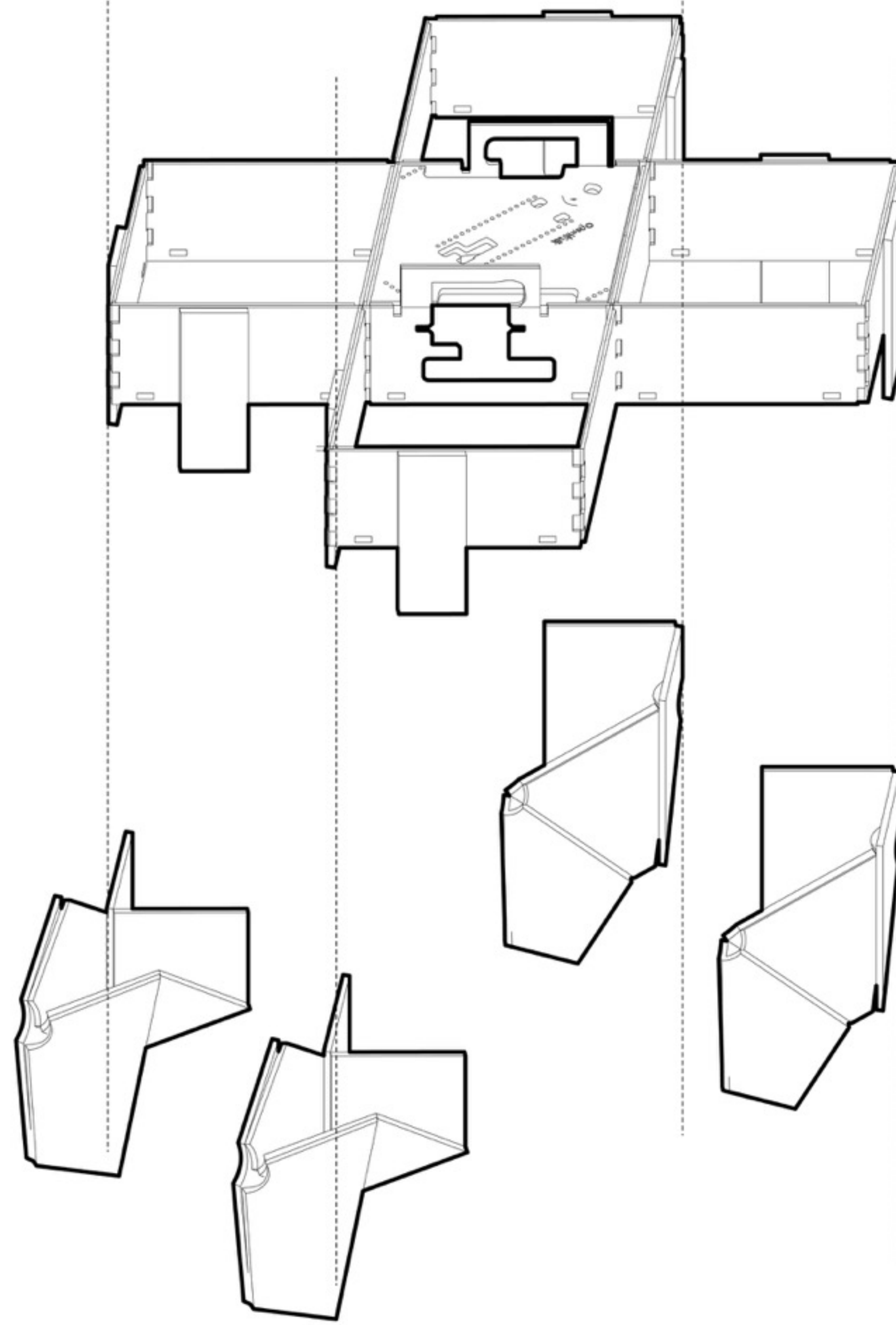


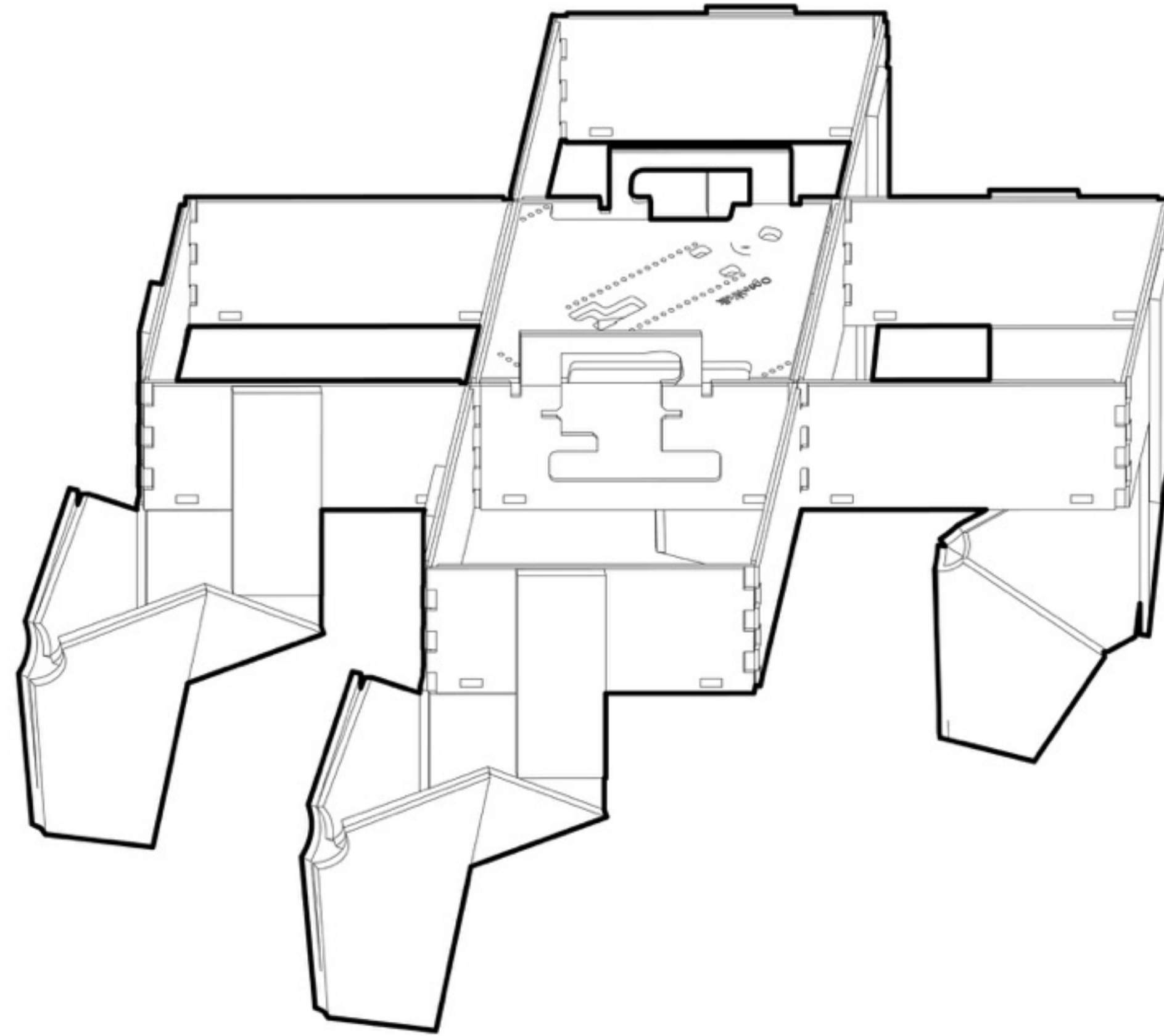
Assembly.

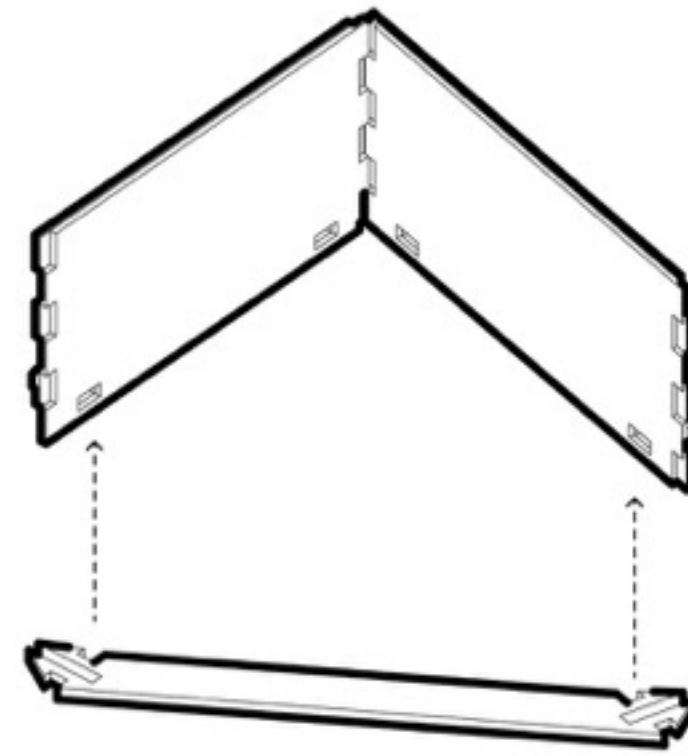


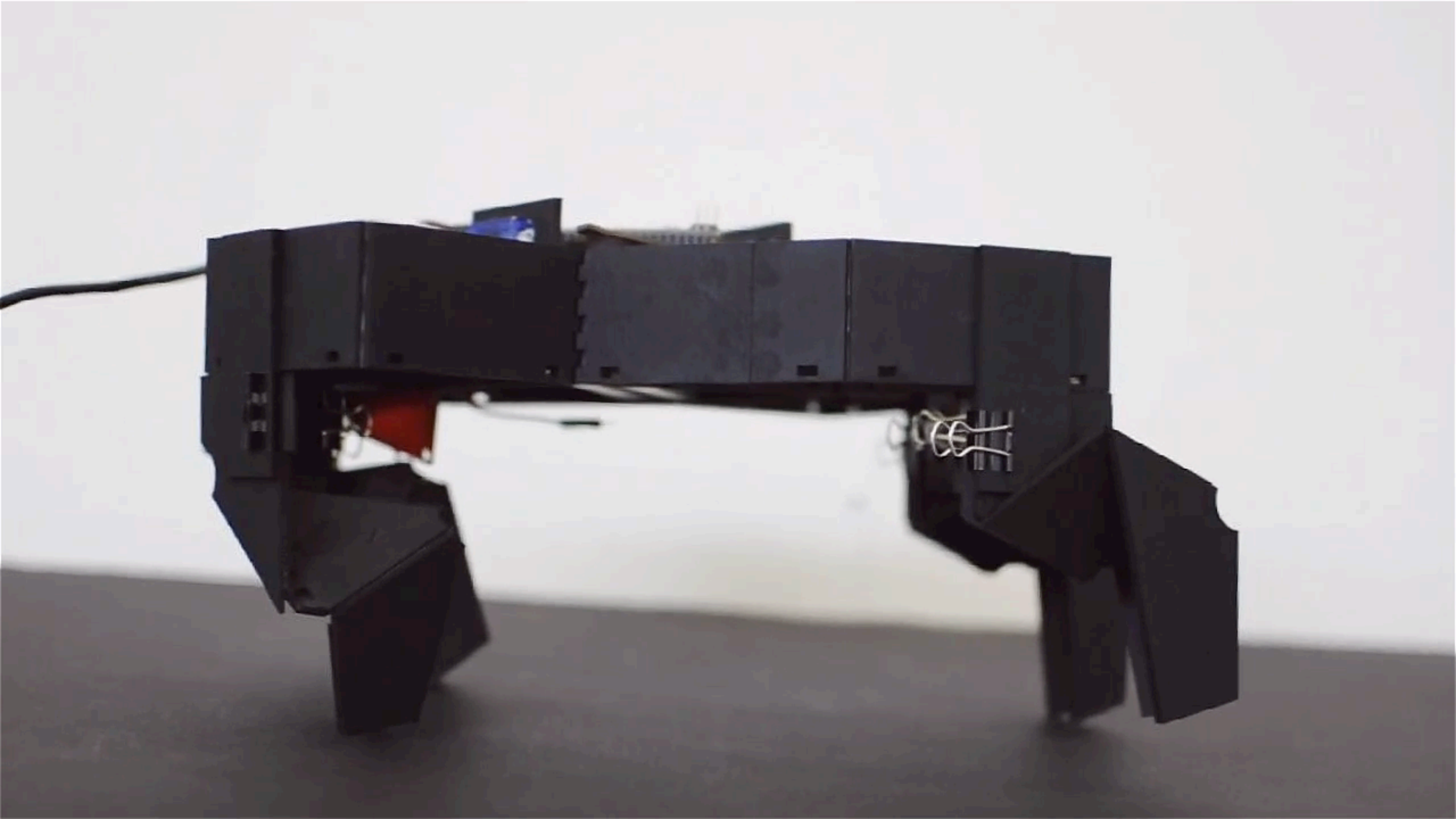






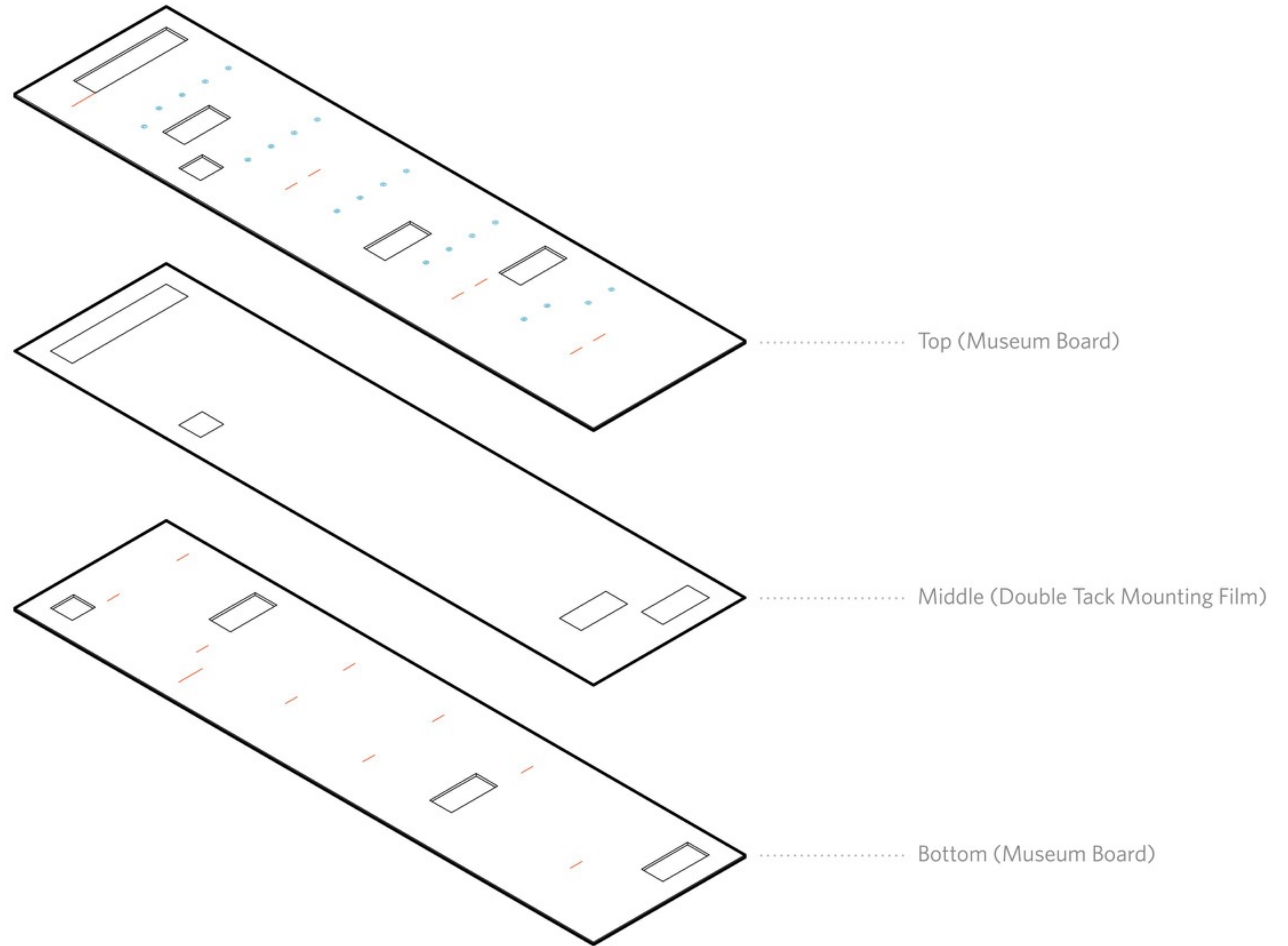


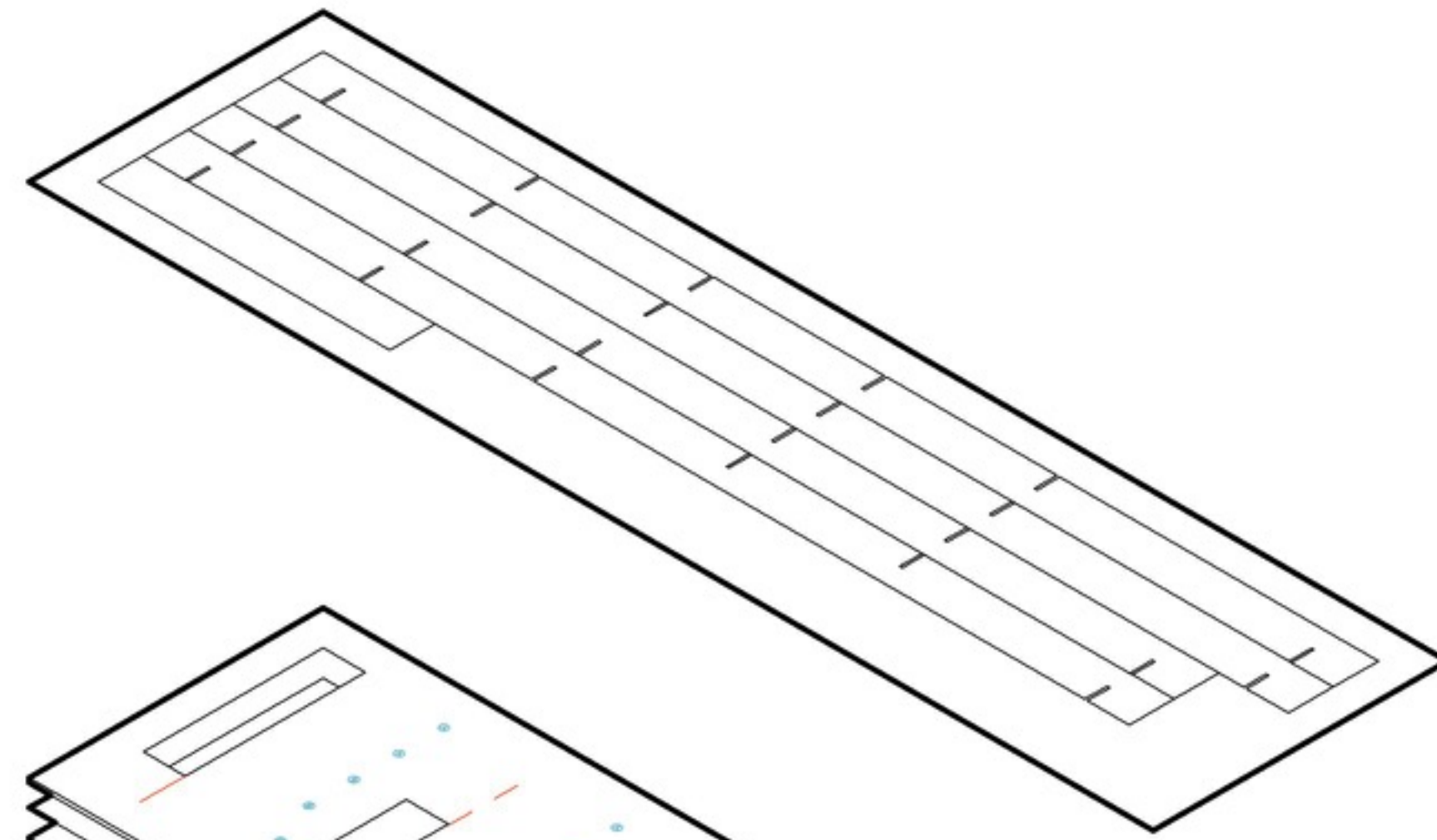




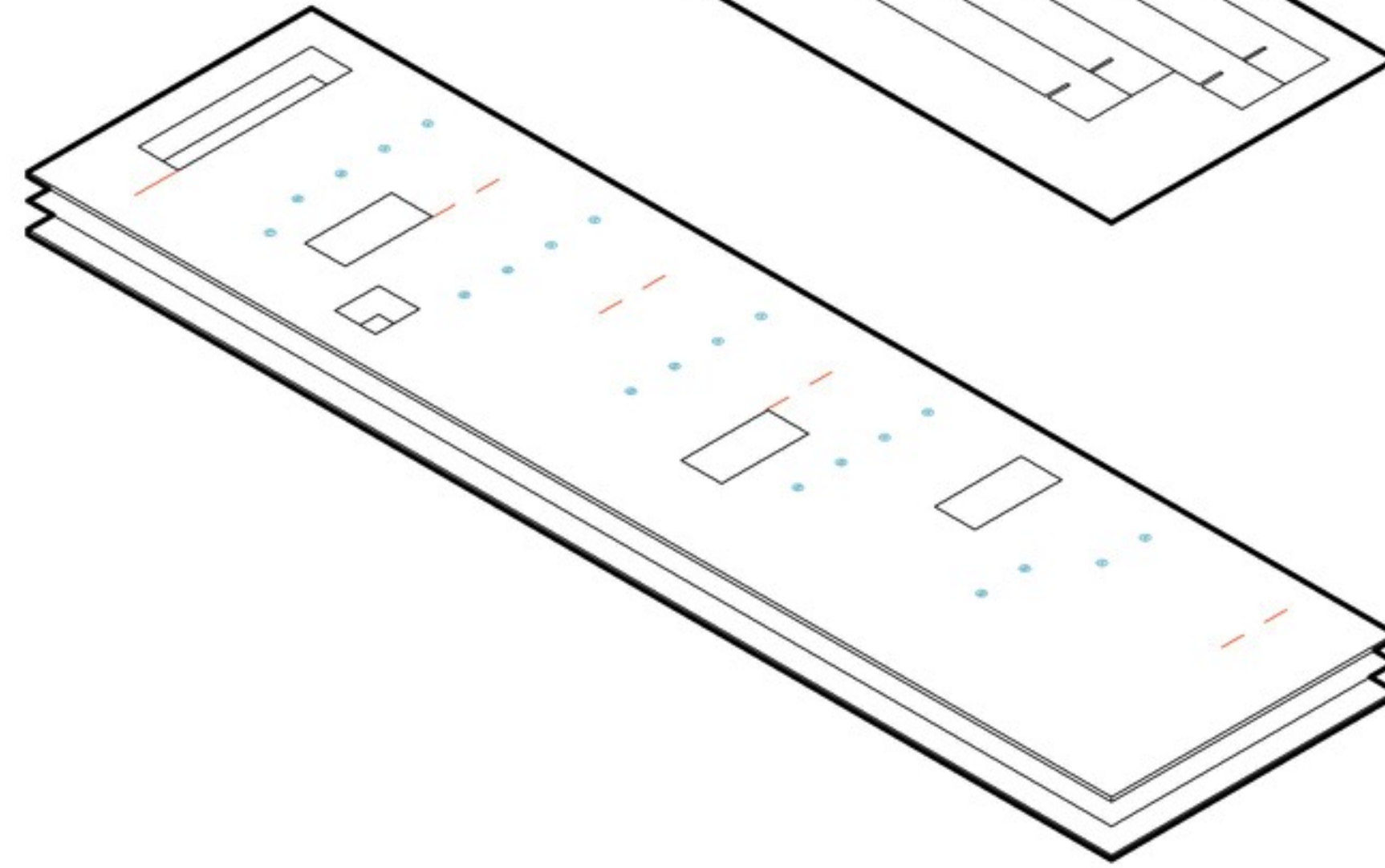
Manufacture.

3 sheets of chipboard (20"x30").
Half letter of YUPO (1/32").
Half letter of Acrylic (1/16").

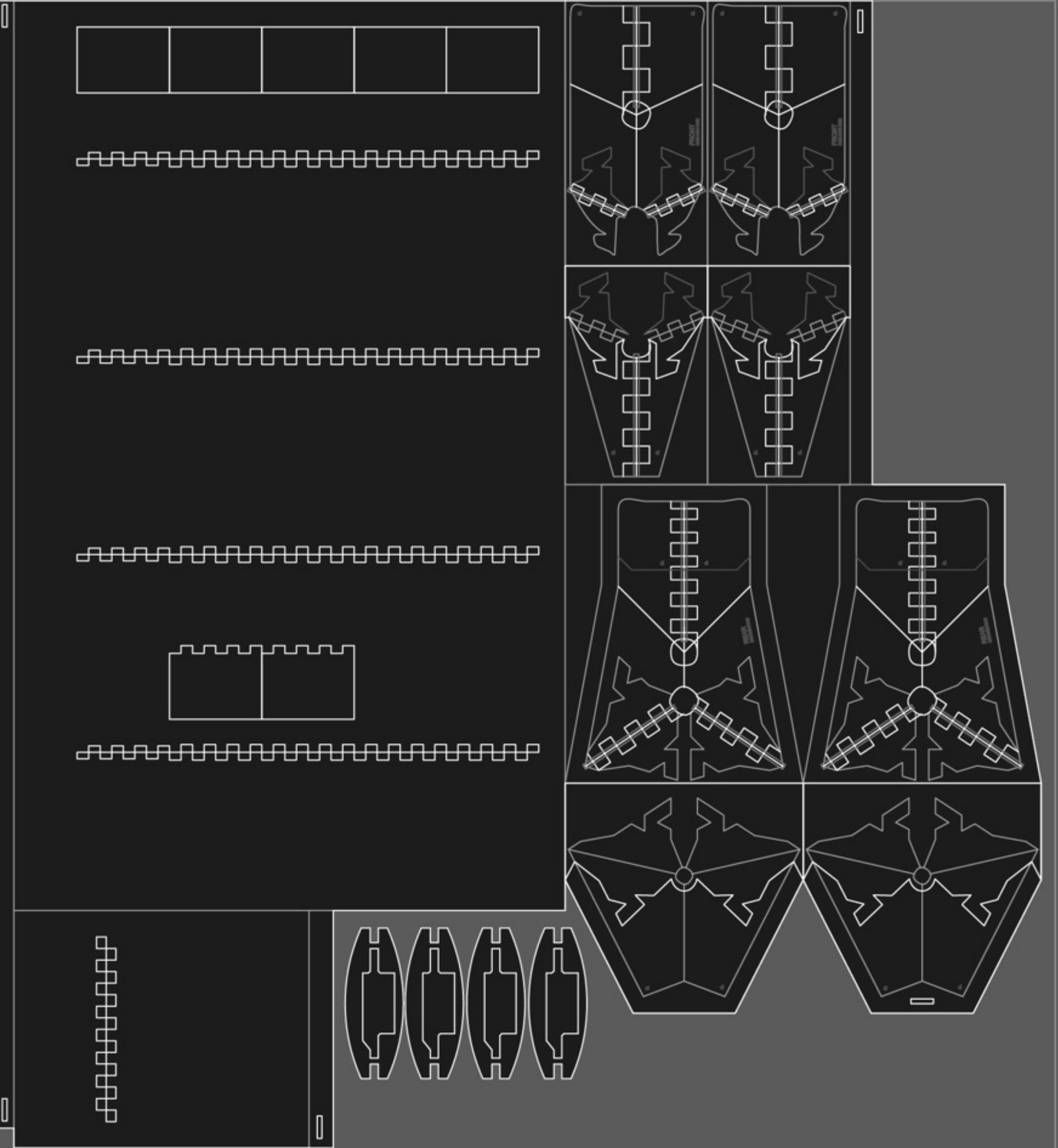
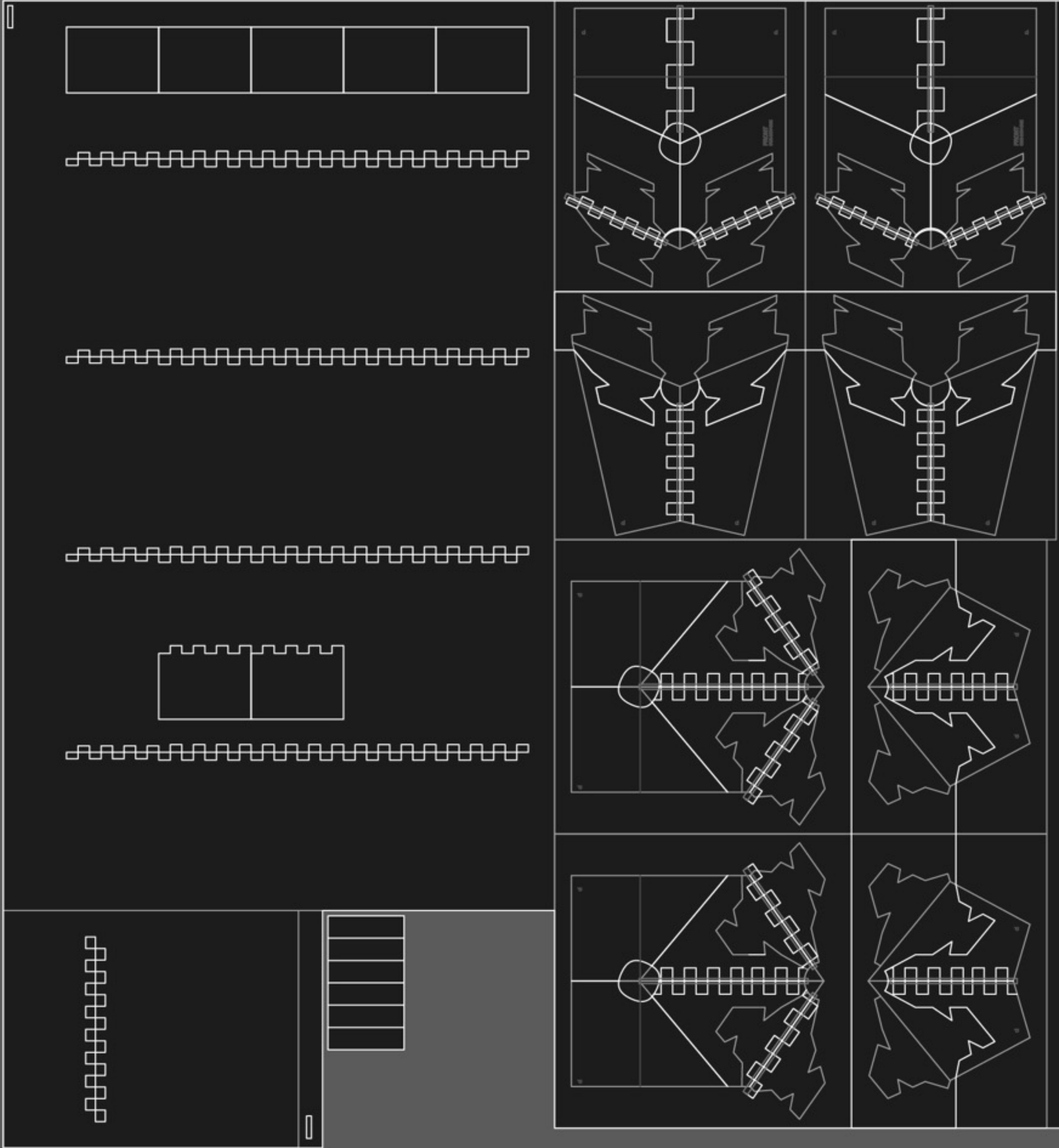


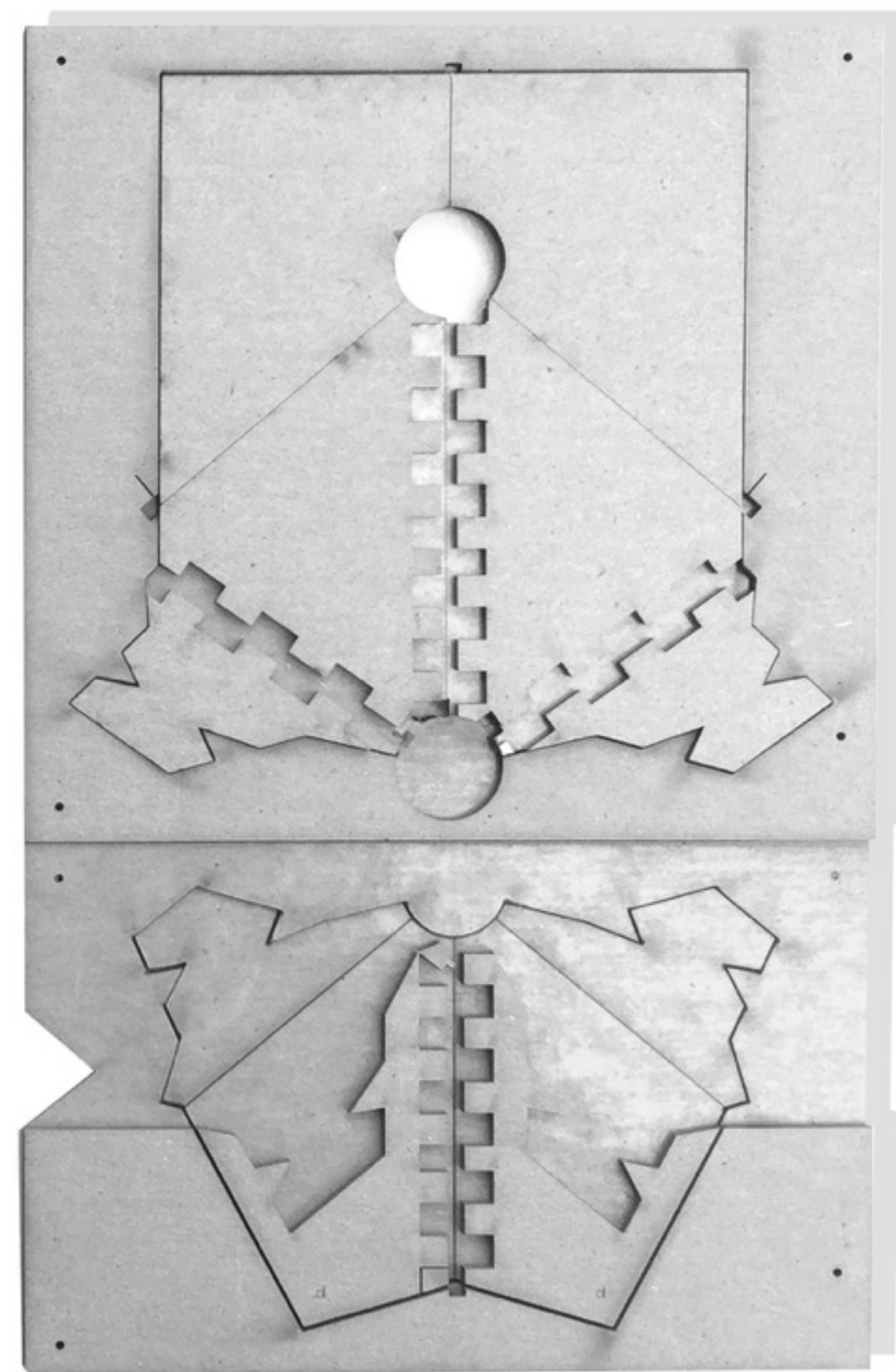
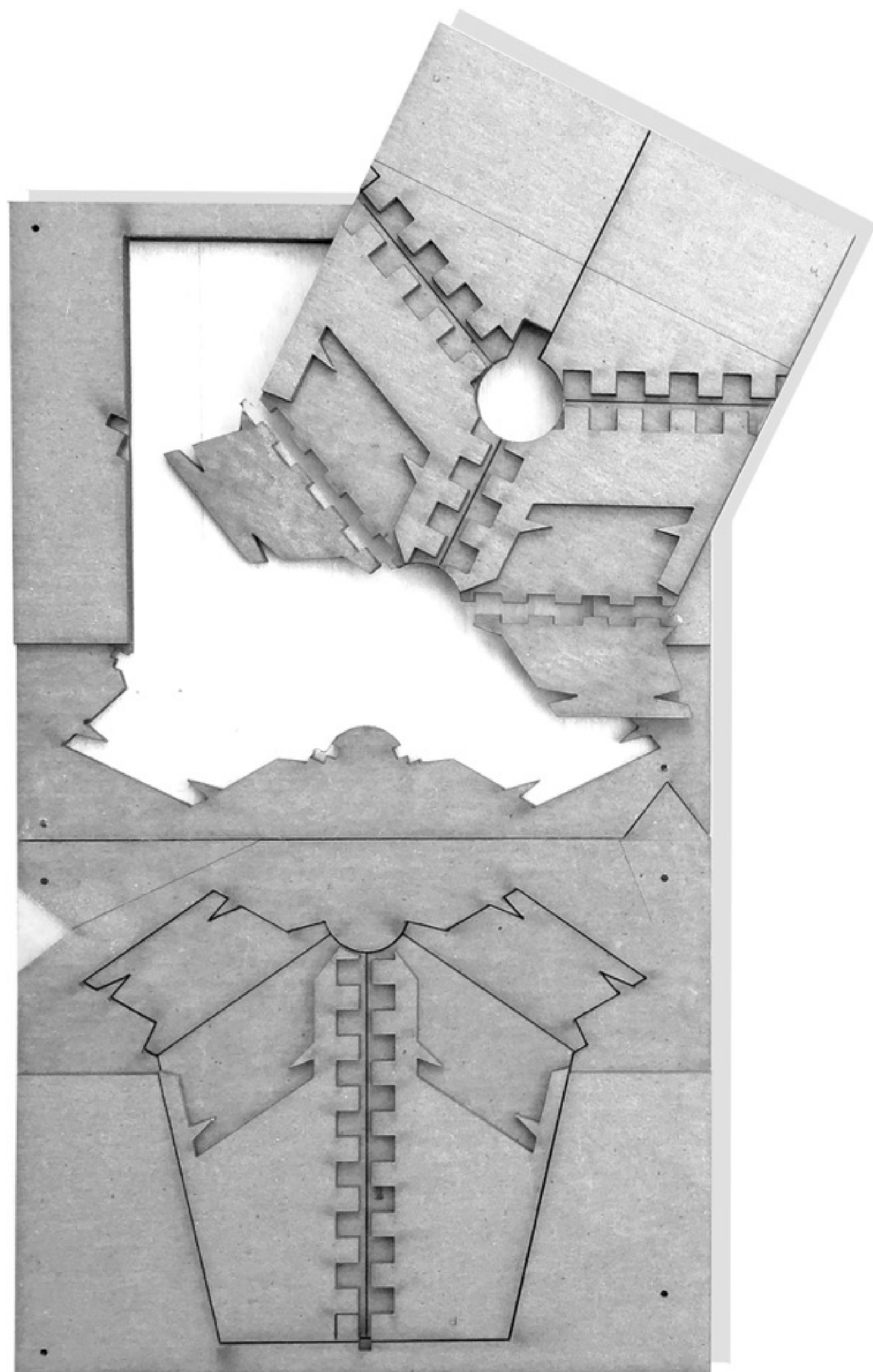


..... Final Cut

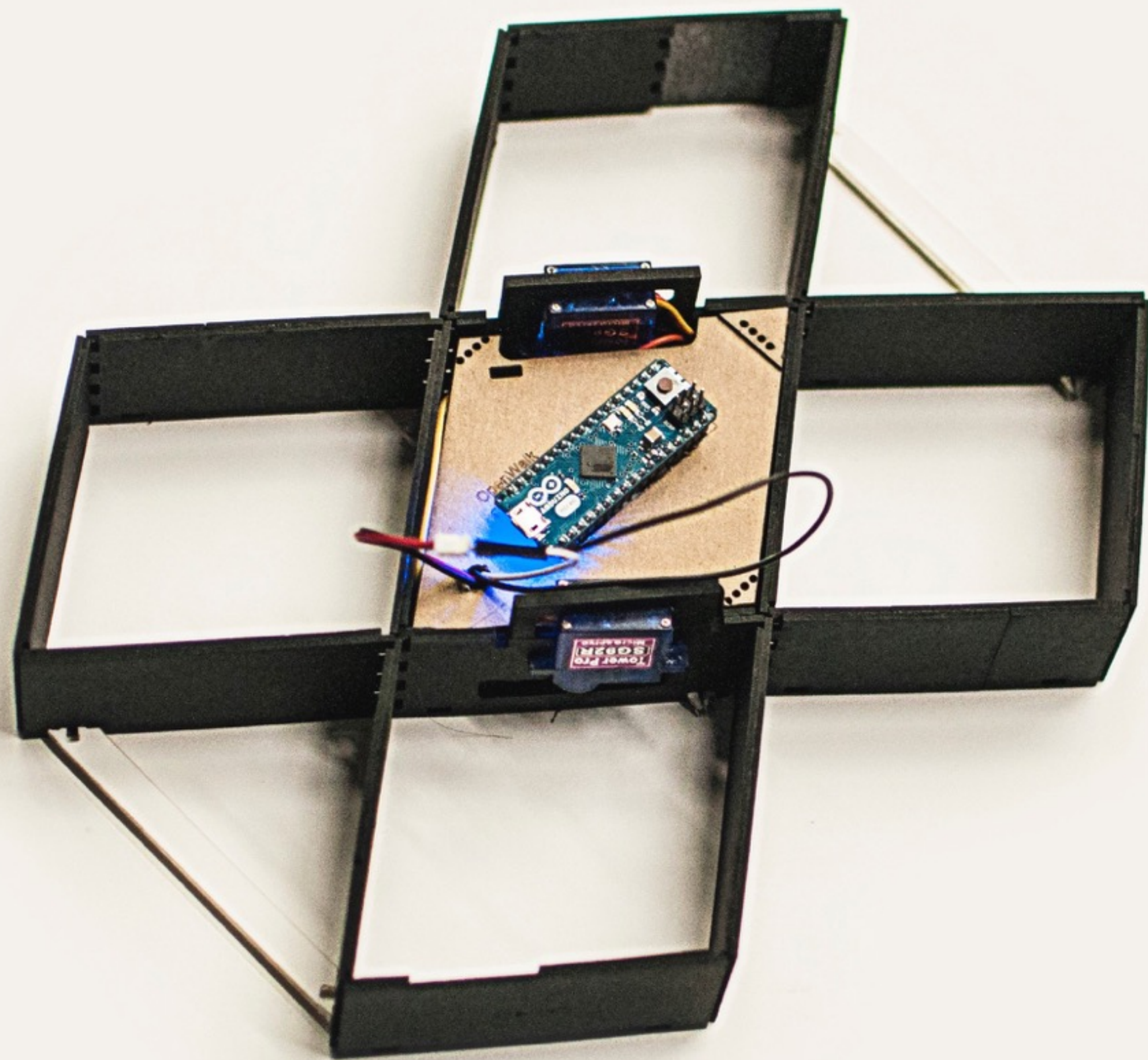


..... Composite



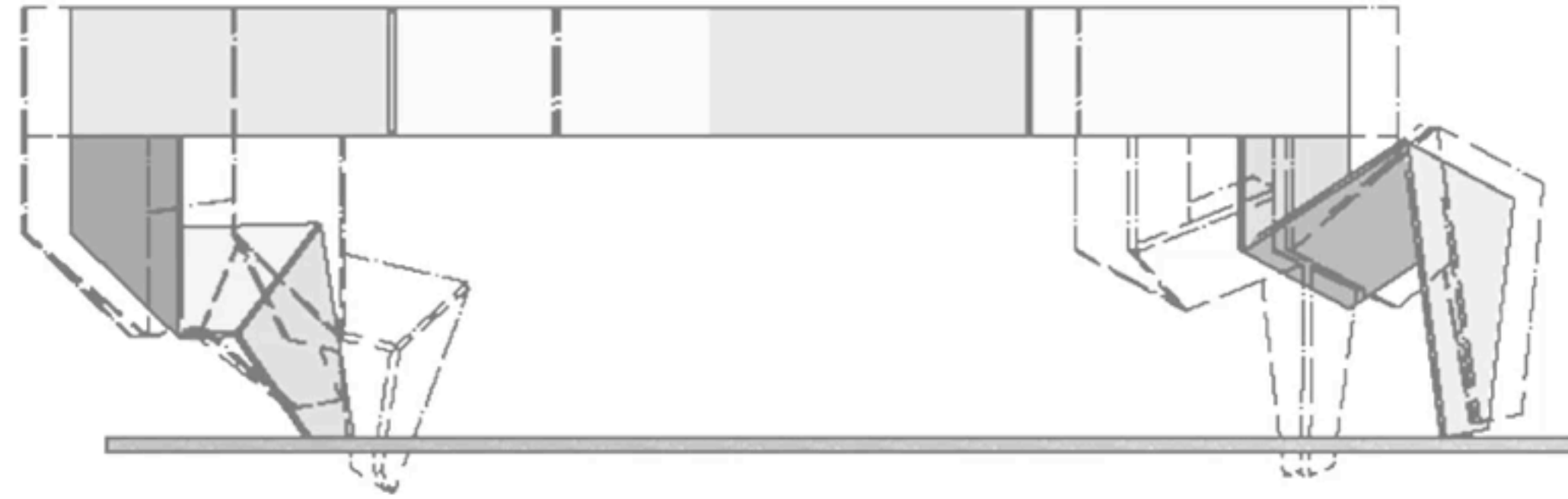
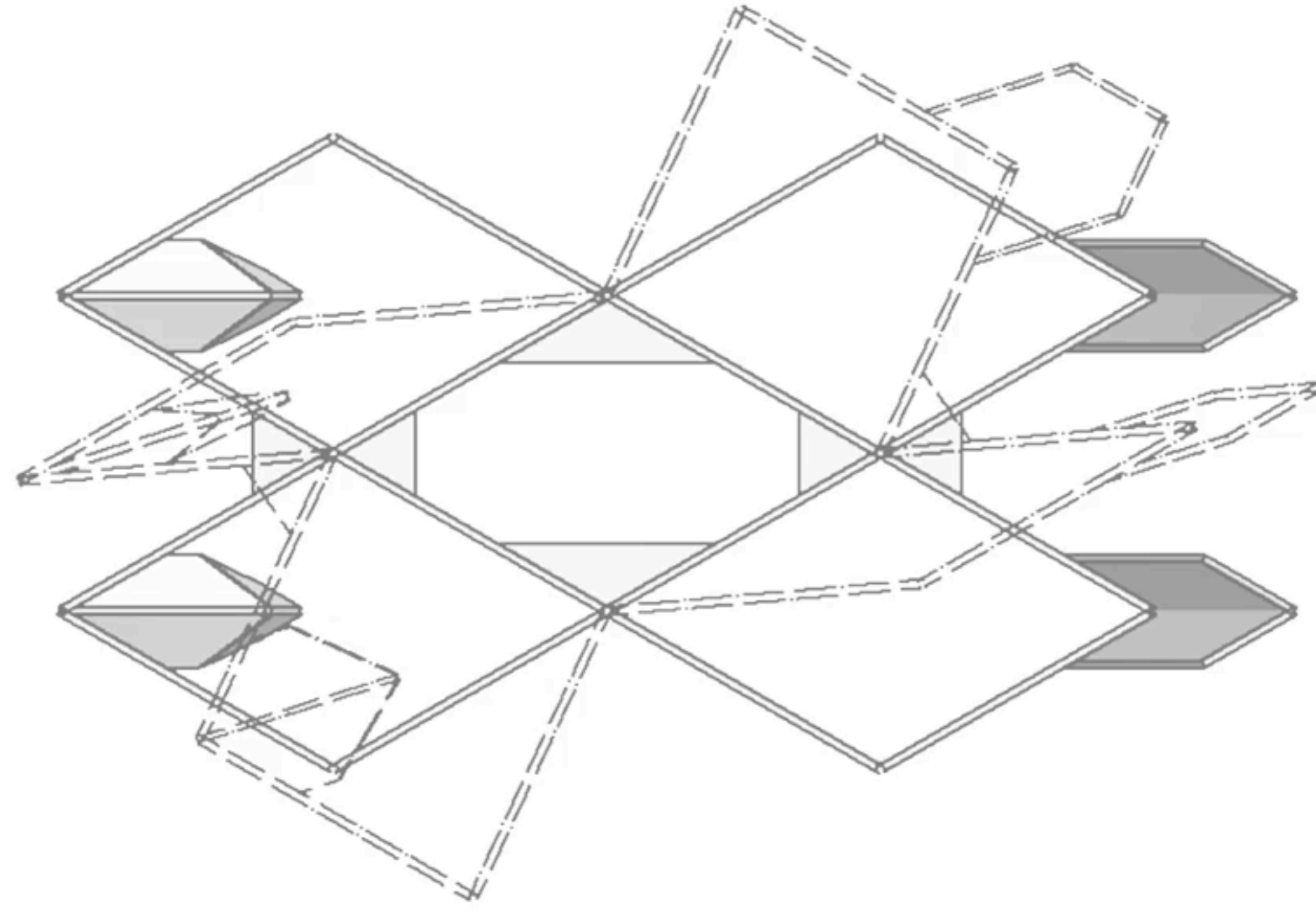


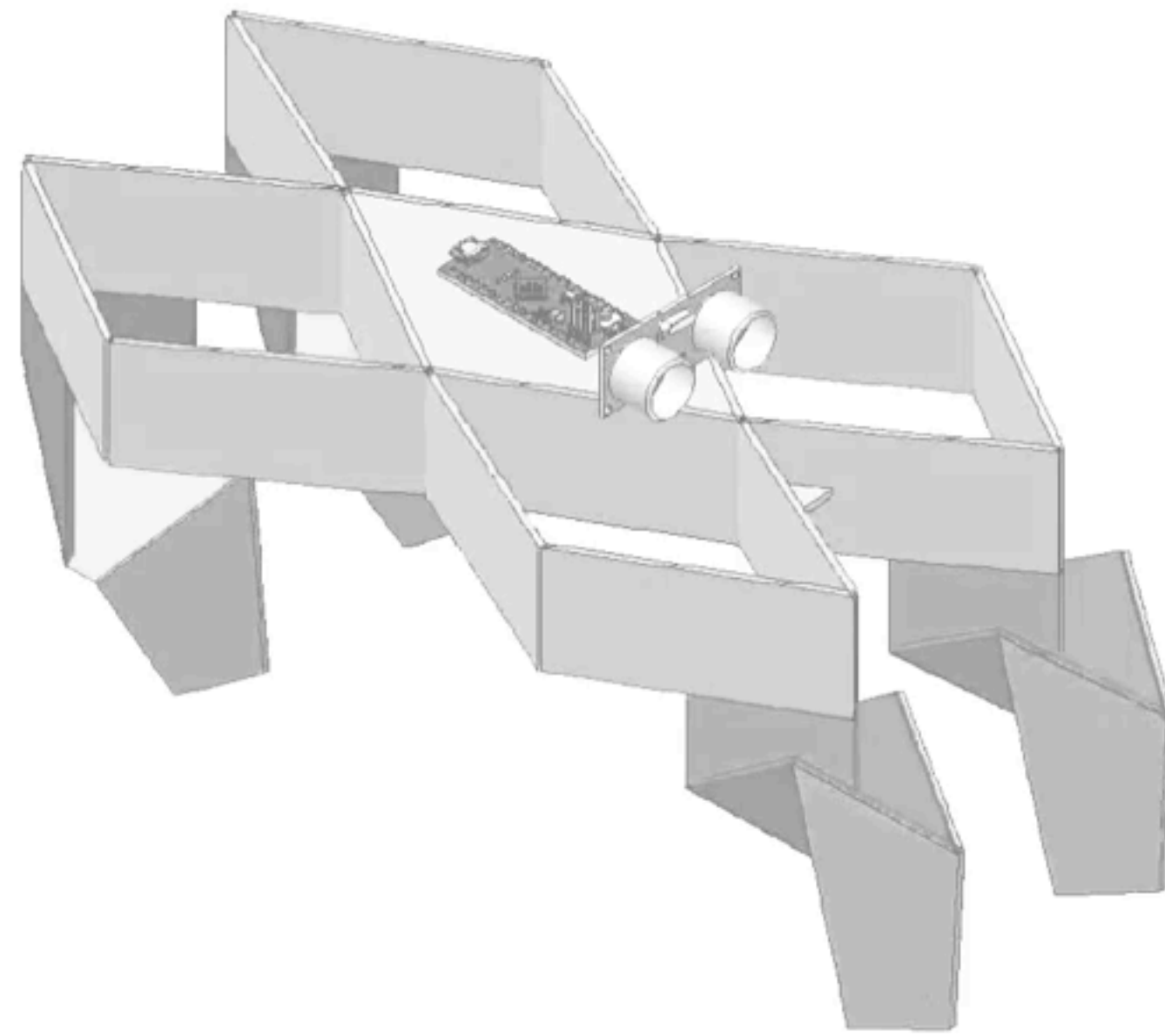
Prototype(s).

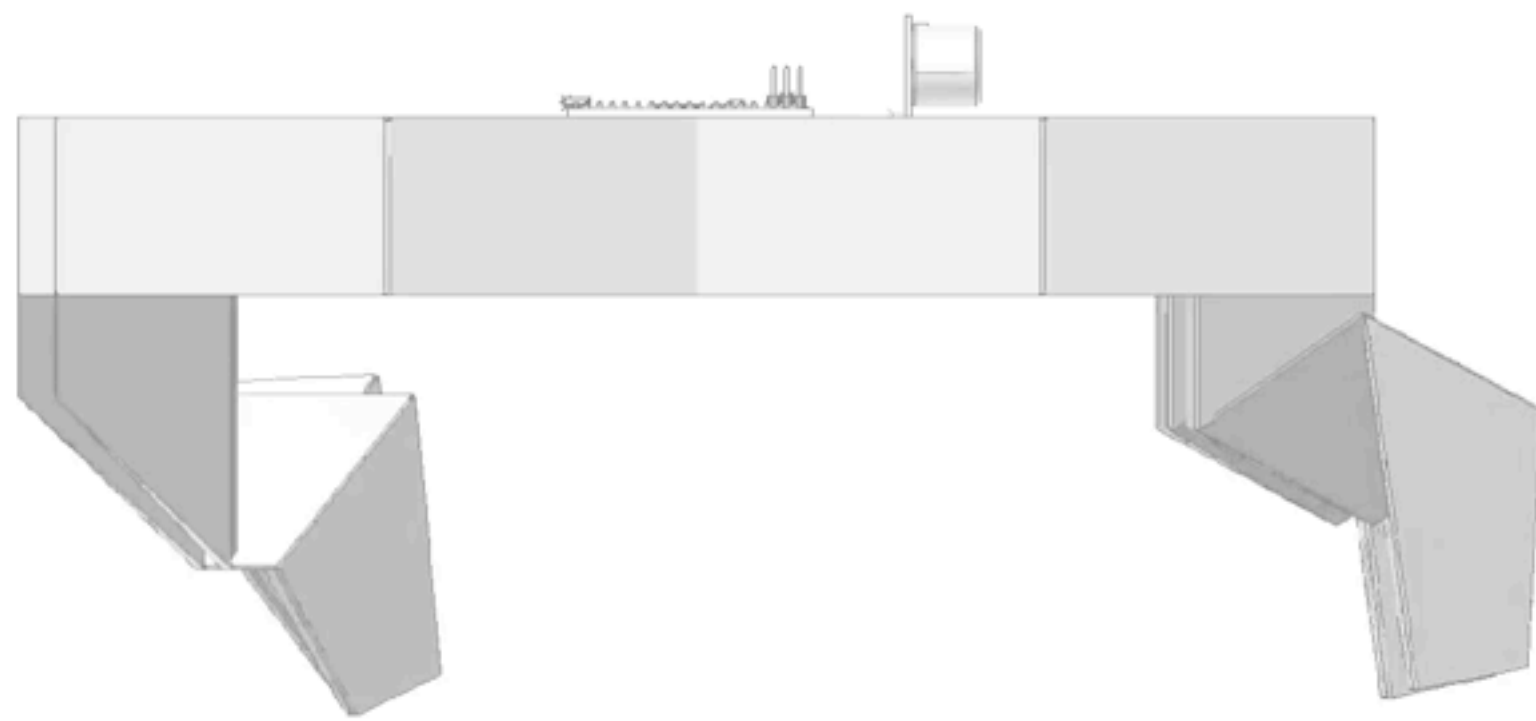


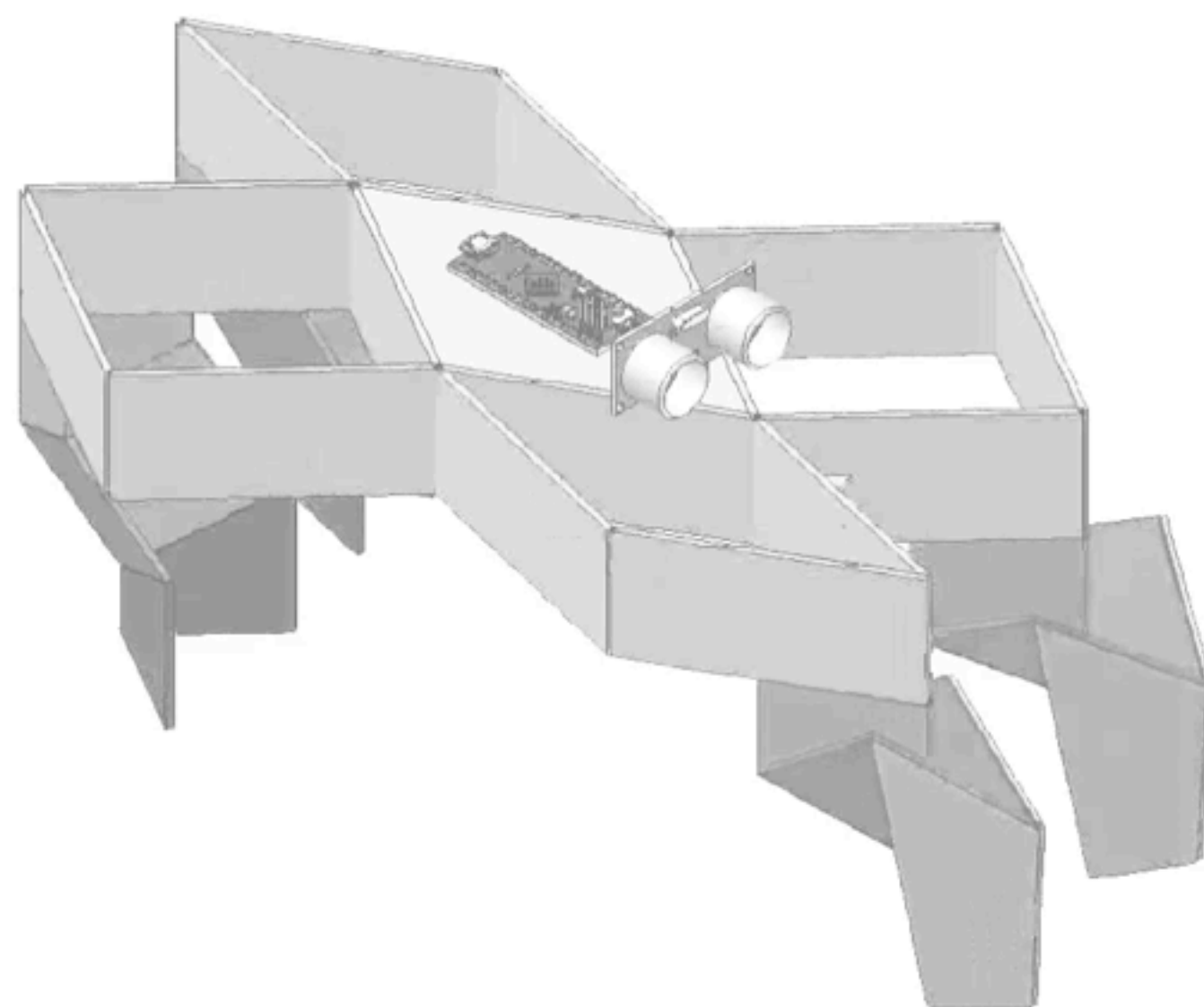
Pictures of prototypes

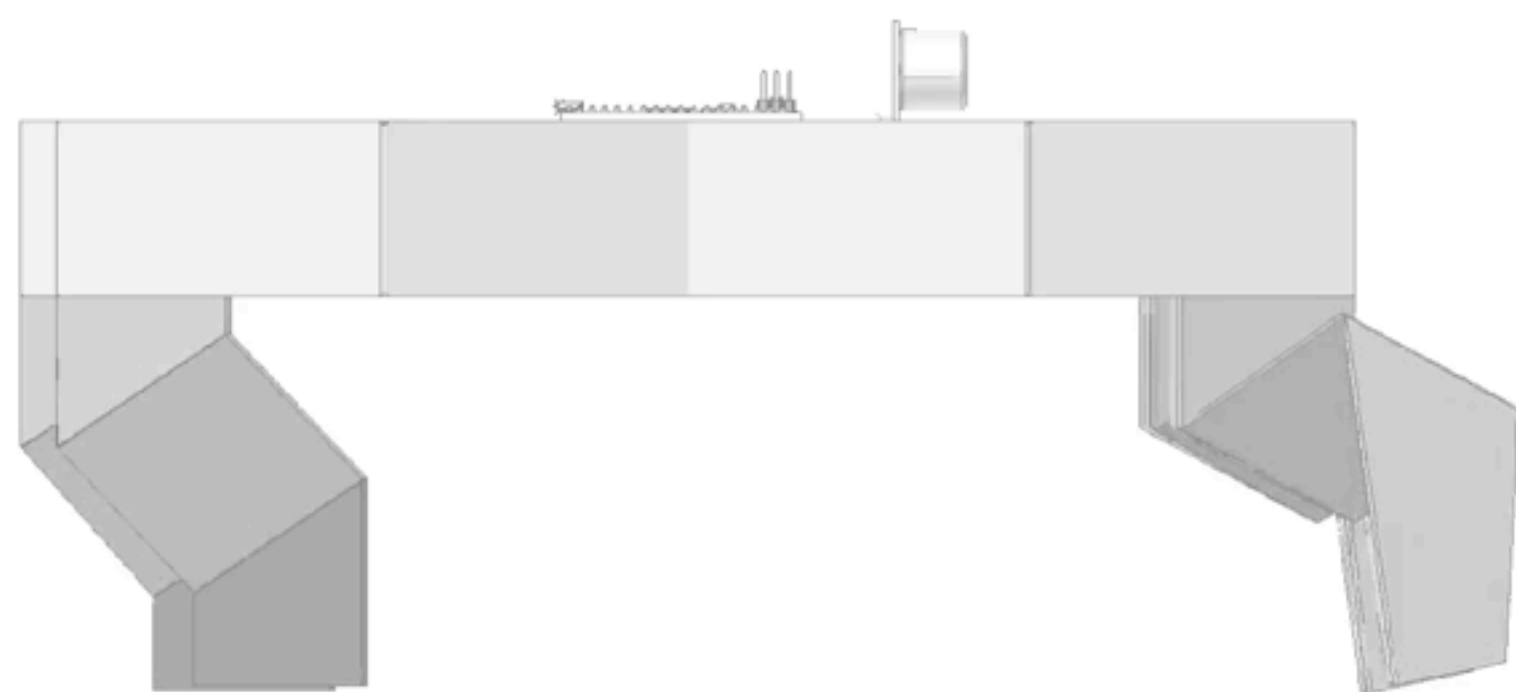
Behavior.

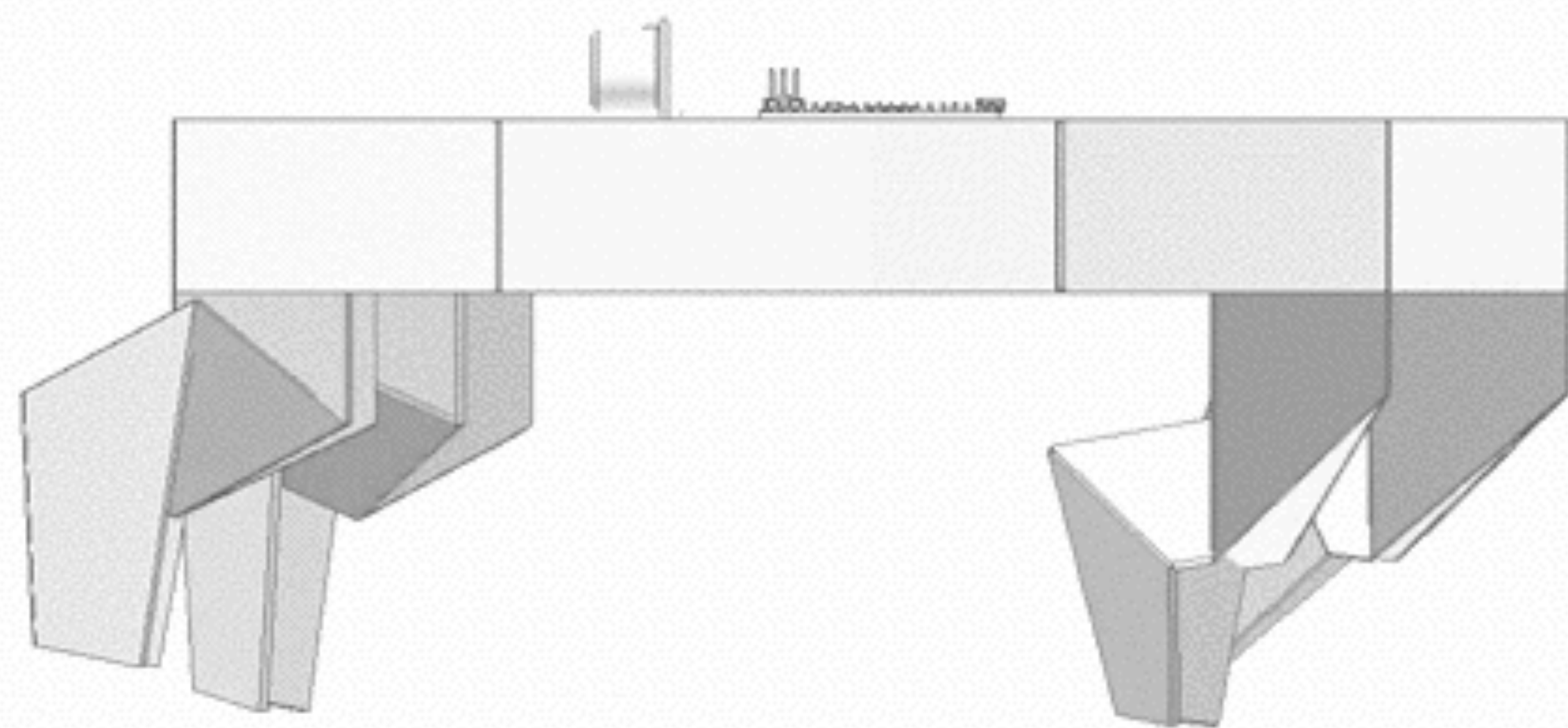


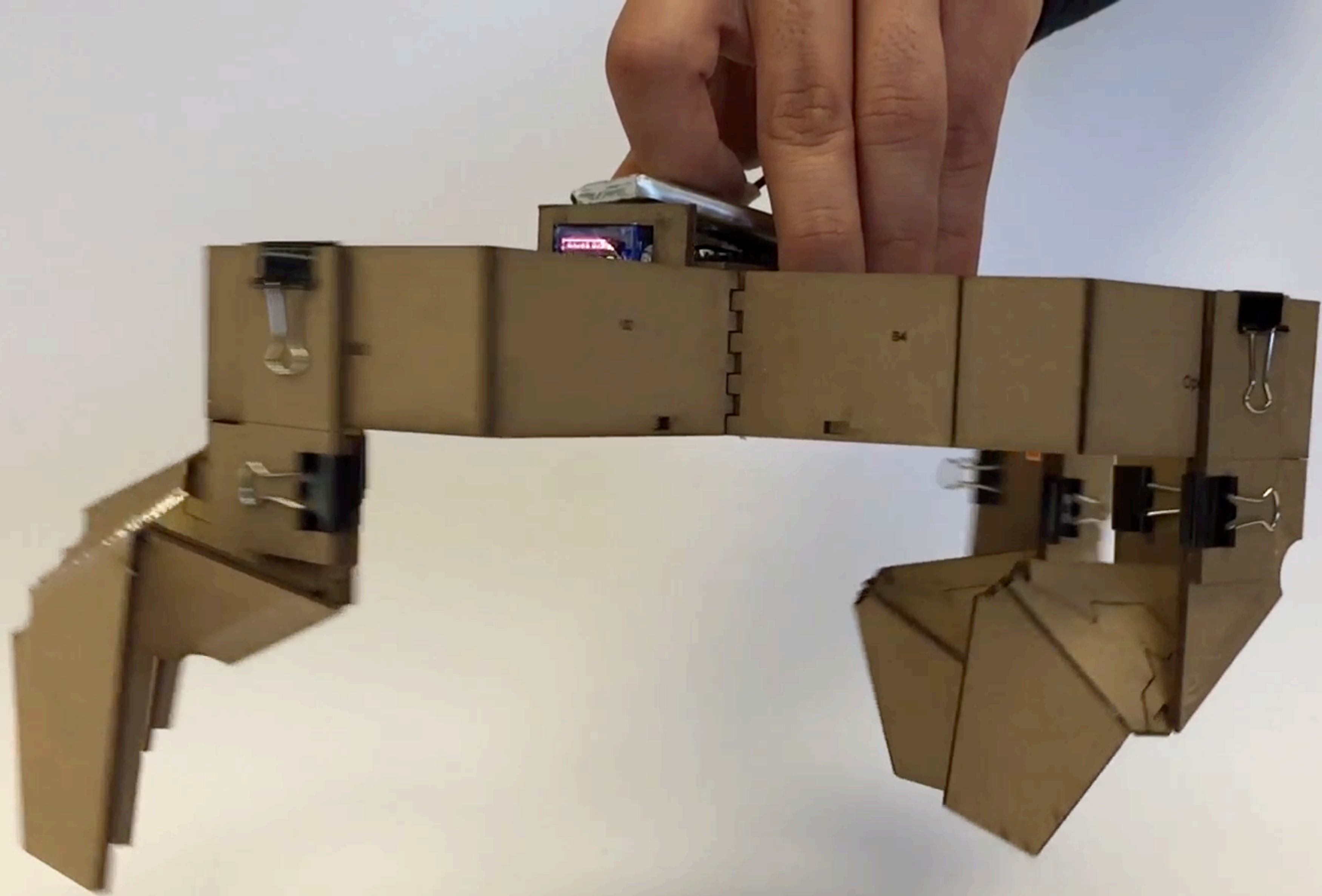


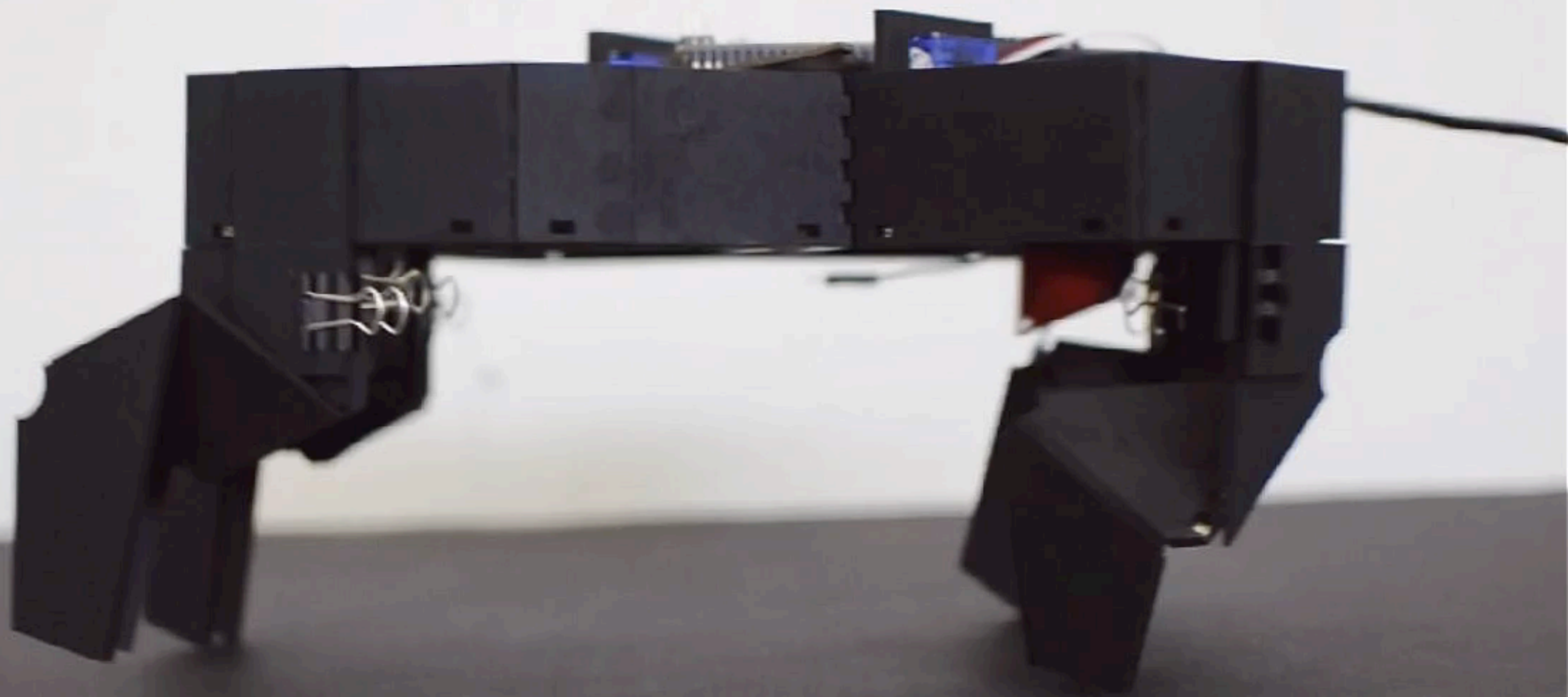


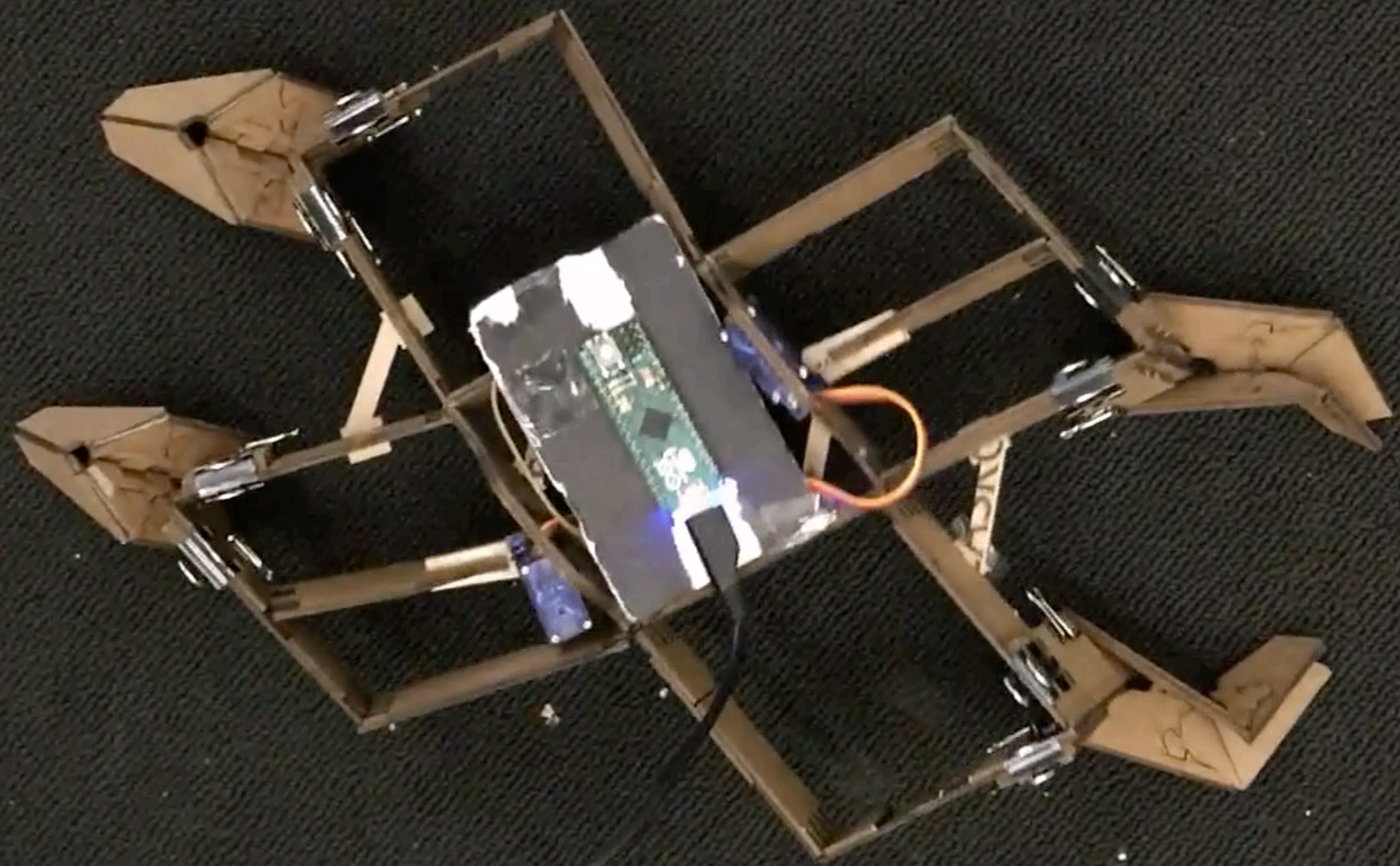












Further Development.



